



OPERATING INSTRUCTIONS

EN

Translation of the Original

TC 400 PB

Electronic drive unit

Dear Customer,

Thank you for choosing a Pfeiffer Vacuum product. Your new electronic drive unit is designed to support you in your individual applications with maximum performance and without malfunctions. The name Pfeiffer Vacuum stands for high-quality vacuum technology, a comprehensive and complete range of top-quality products and first-class service. With this expertise, we have acquired a multitude of skills contributing to an efficient and secure implementation of our product.

Knowing that our product must not interfere with your actual work, we are convinced that our product offers you the solution that supports you in the effective and trouble-free execution of your individual application.

Please read these operating instructions before putting your product into operation for the first time. If you have any questions or suggestions, please feel free to contact info@pfeiffer-vacuum.de.

Further operating instructions from Pfeiffer Vacuum can be found in the [Download Center](#) on our website.

Disclaimer of liability

These operating instructions describe all models and variants of your product. Note that your product may not be equipped with all features described in this document. Pfeiffer Vacuum constantly adapts its products to the latest state of the art without prior notice. Please take into account that online operating instructions can deviate from the printed operating instructions supplied with your product.

Furthermore, Pfeiffer Vacuum assumes no responsibility or liability for damage resulting from the use of the product that contradicts its proper use or is explicitly defined as foreseeable misuse.

Copyright

This document is the intellectual property of Pfeiffer Vacuum and all contents of this document are protected by copyright. They may not be copied, altered, reproduced or published without the prior written permission of Pfeiffer Vacuum.

We reserve the right to make changes to the technical data and information in this document.

Table of contents

1	About this manual	7
1.1	Validity	7
1.2	Applicable documents	7
1.3	Target group	7
1.4	Conventions	7
1.4.1	Instructions in the text	7
1.4.2	Pictographs	7
1.4.3	Stickers on the product	8
1.4.4	Abbreviations	8
1.5	Trademark proof	9
2	Safety	10
2.1	General safety information	10
2.2	Safety instructions	10
2.3	Safety precautions	11
2.4	Limits of use of the product	12
2.5	Proper use	12
2.6	Foreseeable improper use	12
2.7	Functional safety	12
3	Product description	14
3.1	Identifying the product	14
3.2	Product features	14
3.3	Function	14
3.4	Scope of delivery	14
3.5	Connectors	15
4	Installation	16
4.1	Connection diagram	16
4.2	"Profibus" connection	18
4.3	Connection "remote"	18
5	Interfaces	20
5.1	Profibus interface	20
5.1.1	Assign parameterization data	20
5.1.2	Profibus module "PPO1"	21
5.1.3	Profibus module "PPO3"	22
5.1.4	Profibus module "control/status word"	23
5.1.5	Profibus module "control/status byte"	23
5.1.6	Expanded diagnostics data	23
5.2	Pfeiffer Vacuum protocol for RS-485 interface	24
5.2.1	Telegram frame	24
5.2.2	Telegram description	24
5.2.3	Telegram example 1	24
5.2.4	Telegram example 2	25
5.2.5	Data types	25
6	Parameter set	26
6.1	General	26
6.2	Control commands	26
6.3	Status requests	29
6.4	Set value settings	30
6.5	Additional parameters for Profibus	31
6.6	Additional parameters for the control unit	31
7	Operation	33
7.1	Configuring the connections with the Pfeiffer Vacuum parameter set	33

7.1.1	Configure the "remote" connection	33
7.1.2	Configure accessory connections	34
7.1.3	Select interfaces	35
7.2	Operating modes	36
7.2.1	Gas type-dependent operation	36
7.2.2	Set value power consumption	36
7.2.3	Run-up time	37
7.2.4	Rotation speed switch points	37
7.2.5	Rotation speed setting mode	38
7.2.6	Standby	38
7.2.7	Confirming speed specification	39
7.2.8	Backing pump operating modes	39
7.2.9	Backing pump standby mode	40
7.2.10	Operation with accessories	40
7.2.11	Venting modes	41
7.3	Operation via "remote" connection	41
7.3.1	+24 V DC output/pin 1	41
7.3.2	Inputs	42
7.3.3	Outputs	43
7.3.4	Relay contacts (invertible)	44
7.3.5	RS-485	44
7.4	Switching on the turbopump	44
7.5	Switching off the turbopump	45
7.6	Operation monitoring	45
7.6.1	Operating mode display via LED	45
7.6.2	Temperature monitoring	46
8	Recycling and disposal	47
8.1	General disposal information	47
8.2	Dispose of electronic drive unit	47
9	Malfunctions	48
9.1	General	48
9.2	Error codes	48
9.3	Warning and malfunction messages when operating with control units	51
10	Service solutions by Pfeiffer Vacuum	52
	EC Declaration of Conformity	54
	UK Declaration of Conformity	55

List of tables

Tbl. 1:	Stickers on the product	8
Tbl. 2:	Abbreviations used in this document	8
Tbl. 3:	Permissible ambient conditions	12
Tbl. 4:	Data for use in safety-related applications in accordance with IEC 61508 and IEC 62061	12
Tbl. 5:	Data for use in safety-related applications in accordance with EN ISO 13849-1	13
Tbl. 6:	Features of the device variants	14
Tbl. 7:	Connection description of the electronic drive unit	15
Tbl. 8:	Terminal lay-out of "Profibus" M12 connection	18
Tbl. 9:	Terminal lay-out of 26-pin "remote" connection	19
Tbl. 10:	Overview of the Profibus modules	20
Tbl. 11:	Definitions of Profibus parameterization data	21
Tbl. 12:	Profibus module designation in terms of parameterization data	21
Tbl. 13:	Output and input data ("PPO1")	21
Tbl. 14:	Request (output data "PPO1")	21
Tbl. 15:	Response (input data "PPO1")	21
Tbl. 16:	Error numbers (response "PPO1")	22
Tbl. 17:	Control word/status word ("PPO1")	22
Tbl. 18:	Output and input data ("PPO3")	22
Tbl. 19:	Output and input data ("control/status word")	23
Tbl. 20:	Control word/status word ("control/status byte")	23
Tbl. 21:	Profibus: Expanded diagnostics data	23
Tbl. 22:	Explanation and meaning of the parameters	26
Tbl. 23:	Control commands	29
Tbl. 24:	Status requests	30
Tbl. 25:	Set value settings	31
Tbl. 26:	Parameters for Profibus connection	31
Tbl. 27:	Parameters for control unit functions	32
Tbl. 28:	Configure digital outputs and relays [P:019] and [P:024], or [P:045], [P:046], [P:047] and [P:028]	33
Tbl. 29:	Configure digital inputs [P:062], [P:063] and [P:064]	34
Tbl. 30:	Configure analog output [P:055]	34
Tbl. 31:	Configure analog input [P:057]	34
Tbl. 32:	Accessory connections	35
Tbl. 33:	Parameter [P:060]	35
Tbl. 34:	Parameter [P:061]	35
Tbl. 35:	Characteristic nominal rotation speeds of the turbopumps	39
Tbl. 36:	Backing pump operating modes	39
Tbl. 37:	DI1 (release venting) / Pin 2	42
Tbl. 38:	DI motor pump/pin 3	42
Tbl. 39:	DI pumping station / Pin 4	42
Tbl. 40:	DI standby/pin 5	42
Tbl. 41:	DI2 (heater)/pin 6	42
Tbl. 42:	DI3 (sealing gas)/pin 10	43
Tbl. 43:	DI malfunction acknowledgment/pin 13	43
Tbl. 44:	DI remote priority/pin 14	43
Tbl. 45:	RS-485 interface, features	44
Tbl. 46:	Behavior and meaning of the LEDs on the electronic drive unit	45
Tbl. 47:	Behavior and meaning of the Profibus LED	46
Tbl. 48:	Error messages of the electronic drive unit	50
Tbl. 49:	Warning messages of the electronic drive unit	51
Tbl. 50:	Warning and malfunction messages	51

List of figures

Fig. 1:	Standard panel TC 400 PB	14
Fig. 2:	Connection diagram for the electronic drive unit	17
Fig. 3:	Profibus address selector switch	18
Fig. 4:	Illustration of the Profibus modules	20
Fig. 5:	Schematic diagram of power characteristics, example of heavy gases [P:027] = 0	36
Fig. 6:	Rotation speed switch point 1 active	37
Fig. 7:	Rotation speed switch points 1 & 2 active, [P:701] > [P:719]	37
Fig. 8:	Rotation speed switch points 1 & 2 active, [P:701] < [P:719]	38
Fig. 9:	Rotation speed setting mode	43

1 About this manual



IMPORTANT

Read carefully before use.
Keep the manual for future consultation.

1.1 Validity

This operating instructions is a customer document of Pfeiffer Vacuum. The operating instructions describe the functions of the named product and provide the most important information for the safe use of the device. The description is written in accordance with the valid directives. The information in this operating instructions refers to the product's current development status. The document shall remain valid provided that the customer does not make any changes to the product.

1.2 Applicable documents

TC 400 PB	Operating instructions
Declaration of conformity	A component of these instructions

You can find this document in the [Pfeiffer Vacuum Download Center](#).

1.3 Target group

These operating instructions are aimed at all persons performing the following activities on the product:

- Transportation
- Setup (Installation)
- Usage and operation
- Decommissioning
- Maintenance and cleaning
- Storage or disposal

The work described in this document is only permitted to be performed by persons with the appropriate technical qualifications (expert personnel) or who have received the relevant training from Pfeiffer Vacuum.

1.4 Conventions

1.4.1 Instructions in the text

Usage instructions in the document follow a general structure that is complete in itself. The required action is indicated by an individual step or multi-part action steps.

Individual action step

A horizontal, solid triangle indicates the only step in an action.

- This is an individual action step.

Sequence of multi-part action steps

The numerical list indicates an action with multiple necessary steps.

1. Step 1
2. Step 2
3. ...

1.4.2 Pictographs

Pictographs used in the document indicate useful information.



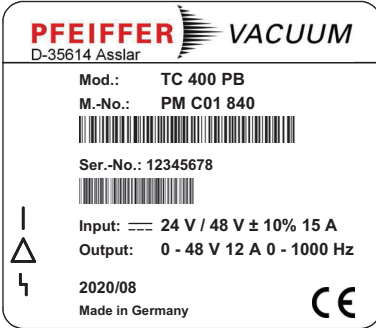

Note



Tip

1.4.3 Stickers on the product

This section describes all the stickers on the product along with their meanings.

	Rating plate The rating plate is located on the side of the electronic drive unit.
	Warranty seal The product is sealed ex-factory. Damaging or removing a warranty seal results in loss of the warranty.

Tbl. 1: Stickers on the product

1.4.4 Abbreviations

Abbreviation	Meaning in this document
AI/AO	Analog input/analog output
AIC	Ampere Interrupting Capacity
DC	Direct current
DI/DO	Digital input/digital output
f	Rotation speed value of a vacuum pump (frequency, in rpm or Hz)
I	Electric amperage
LED	Light emitting diode
[P:xxx]	Electronic drive unit control parameters. Printed in bold as a three-digit number in square brackets. Frequently displayed in conjunction with a short description Example: [P:312] software version
P	Electrical power
PE	Protective ground (earth)
R	Electrical resistance
remote	26-pole D-Sub connecting socket on the turbopump electronic drive unit
RS-485	Standard for a physical interface for asynchronous serial data transmission (Recommended Standard)
t	Time
TC	Electronic drive unit (turbo controller)
TMS	Temperature management system
U	Electric voltage

Tbl. 2: Abbreviations used in this document

1.5 Trademark proof

- Profibus® is a registered trading name of Profibus Nutzerorganisation e.V.

2 Safety

2.1 General safety information

The following 4 risk levels and 1 information level are taken into account in this document.

DANGER

Immediately pending danger

Indicates an immediately pending danger that will result in death or serious injury if not observed.

- Instructions to avoid the danger situation

WARNING

Potential pending danger

Indicates a pending danger that could result in death or serious injury if not observed.

- Instructions to avoid the danger situation

CAUTION

Potential pending danger

Indicates a pending danger that could result in minor injuries if not observed.

- Instructions to avoid the danger situation

NOTICE

Danger of damage to property

Is used to highlight actions that are not associated with personal injury.

- Instructions to avoid damage to property



Notes, tips or examples indicate important information about the product or about this document.

2.2 Safety instructions

All safety instructions in this document are based on the results of the risk assessment carried out in accordance with Low Voltage Directive 2014/35/EU. Where applicable, all life cycle phases of the product were taken into account.

Risks during installation

DANGER

Danger to life from electric shock

Power supply packs that are not specified or are not approved will lead to severe injury to death.

- Make sure that the power supply pack meets the requirements for double isolation between mains input voltage and output voltage, in accordance with IEC 61010-1 IEC 60950-1 and IEC 62368-1.
- Make sure that the power supply pack meets the requirements in accordance with IEC 61010-1 IEC 60950-1 and IEC 62368-1.
- Where possible, use original power supply packs or only power supply packs that correspond with the applicable safety regulations.

⚠ DANGER**Danger to life from electric shock**

When establishing the voltages that exceed the specified safety extra-low voltage (according to IEC 60449 and VDE 0100), the insulating measures will be destroyed. There is a danger to life from electric shock at the communication interfaces.

- ▶ Connect only suitable devices to the bus system.

⚠ WARNING**Risk of injury due to incorrect installation**

Dangerous situations may arise from unsafe or incorrect installation.

- ▶ Do not carry out your own conversions or modifications on the unit.
- ▶ Ensure the integration into an Emergency Off safety circuit.

Risks in the event of malfunctions**⚠ WARNING****Risk of injury from parts moving after a power failure or troubleshooting**

The "pumping station" function of the electronic drive unit will remain active after a power failure or if errors occur that shut down the vacuum pump or the system. When power is restored or after acknowledging a fault, the vacuum pump runs up automatically. There is a risk of injury to fingers and hands if they enter the operating range of rotating parts.

- ▶ Always keep the mains connection freely accessible so you can disconnect it at any time.
- ▶ Remove present mating plugs or bridges from the electronic drive unit possibly before the mains power returns, as these can cause an automatic run-up.
- ▶ Switch the pump off using the "Pumping station" function (parameter **[P:010]**).

2.3 Safety precautions

**Duty to provide information on potential dangers**

The product holder or user is obliged to make all operating personnel aware of dangers posed by this product.

Every person who is involved in the installation, operation or maintenance of the product must read, understand and adhere to the safety-related parts of this document.

**Infringement of conformity due to modifications to the product**

The Declaration of Conformity from the manufacturer is no longer valid if the operator changes the original product or installs additional equipment.

- Following the installation into a system, the operator is required to check and re-evaluate the conformity of the overall system in the context of the relevant European Directives, before commissioning that system.

General safety precautions when handling the product

- ▶ Use only power supply packs that comply with the applicable safety regulations.
- ▶ Observe all applicable safety and accident prevention regulations.
- ▶ Check that all safety measures are observed at regular intervals.
- ▶ Recommendation: Establish a secure connection to the earthed conductor (PE); protection class III.
- ▶ Never disconnect plug connections during operation.
- ▶ Keep lines and cables away from hot surfaces ($> 70\text{ °C}$).
- ▶ Do not carry out your own conversions or modifications on the unit.
- ▶ Observe the unit protection class prior to installation or operation in other environments.
- ▶ Observe the protection class by ensuring the correct seating of the present sealing plugs.
- ▶ Disconnect the electronic drive unit only once everything has come to a complete standstill and when the mains power supply of the turbopump is interrupted.

2.4 Limits of use of the product

Installation location	weatherproof (internal space)
Air pressure	750 hPa to 1060 hPa
Installation altitude	max. 5000 m
Rel. air humidity	max. 80 %, at $T \leq 31\text{ }^{\circ}\text{C}$, up to max. 50% at $T \leq 40\text{ }^{\circ}\text{C}$
Protection class	III
Excess voltage category	II
Permissible protection degree	IP54
Degree of contamination	2
Ambient temperature	+5 °C to +40 °C

Tbl. 3: Permissible ambient conditions



Notes on ambient conditions

The specified permissible ambient temperatures apply to operation of the turbopump at maximum permissible backing pressure or at maximum gas throughput, depending on the cooling type. The turbopump is intrinsically safe thanks to redundant temperature monitoring.

- The reduction in backing pressure or gas throughput permits operation of the turbopump at higher ambient temperatures.
- If the maximum permissible operating temperature of the turbopump is exceeded, the electronic drive unit first reduces the drive output and then switches it off where necessary.

2.5 Proper use

- The electronic drive unit is used exclusively for the operation of Pfeiffer Vacuum turbopumps and their accessories with a Profibus DP®bus system.

2.6 Foreseeable improper use

Improper use of the product invalidates all warranty and liability claims. Any use that is counter to the purpose of the product, whether intentional or unintentional, is regarded as misuse, in particular:

- Connection to power supplies that do not comply with the provisions of IEC 61010 or IEC 60950
- Operation with excessively high irradiated heat output
- Use in areas with ionizing radiation
- Operation in explosion-hazard areas
- Use of accessories or spare parts that are not listed in these instructions

2.7 Functional safety

The TC 400 PB drive unit (electronic drive unit) executes the “Safe Limited Speed” safety function in accordance with EN 61800-5-2. In the event of excess rotation speed, the vacuum pump motor’s commutation switches off and brings the drive into a safe state.

Summary of characteristic data for use in safety-related applications:

Characteristics in accordance with IEC 61508 and IEC 62061				
Characteristic	Safety Integrity Level	PFH	PFD _{av}	Proof Test Interval T
Value	SIL CL 2	$1.1 \cdot 10^{-8} / \text{h}$	$1 \cdot 10^{-3}$	20 a

Tbl. 4: Data for use in safety-related applications in accordance with IEC 61508 and IEC 62061






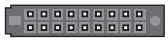
Characteristics in accordance with EN ISO 13849-1

Characteristic	Performance Level	Category	MTTF _d	Average diagnostic coverage DC
Value	PL d	Cat. 3	high (135 a)	medium (90 % - < 99 %)

Tbl. 5: Data for use in safety-related applications in accordance with EN ISO 13849-1

- No proof test is required throughout the expected device lifetime of up to 20 years.
- If you calculate your safety application with the specified values for 20 years, you will need to de-commission the safety controller and return it to the manufacturer after 20 years. You must not perform a proof test.

3.5 Connectors

	DC in¹⁾ Housing connector with bayonet mount for the voltage supply between Pfeiffer Vacuum power supply packs and the electronic drive unit.
	accessory M12 bushing with screw lock for the connection of Pfeiffer Vacuum accessories. The use of a Y-connector permits the double pinout of a connector.
	PV.can M12 socket with screw lock and LED for the connection of an integrated pressure measurement and for Pfeiffer Vacuum service purposes.
	remote High-density sub-D bushing with 26 pins for connection and configuration of a remote control.
	Profibus M12 bushing (B-coded) with threaded coupling and LED for connecting Profibus DP [®] bus systems.
	Device socket on the rear side of the electronic drive unit for the connection of the turbopump.

Tbl. 7: Connection description of the electronic drive unit

1) "DC in" and "accessory" are described in the operating instructions of the turbopump.

4 Installation

4.1 Connection diagram

DANGER

Danger to life from electric shock

Power supply packs that are not specified or are not approved will lead to severe injury to death.

- ▶ Make sure that the power supply pack meets the requirements for double isolation between mains input voltage and output voltage, in accordance with IEC 61010-1 IEC 60950-1 and IEC 62368-1.
- ▶ Make sure that the power supply pack meets the requirements in accordance with IEC 61010-1 IEC 60950-1 and IEC 62368-1.
- ▶ Where possible, use original power supply packs or only power supply packs that correspond with the applicable safety regulations.

DANGER

Danger to life from electric shock

When establishing the voltages that exceed the specified safety extra-low voltage (according to IEC 60449 and VDE 0100), the insulating measures will be destroyed. There is a danger to life from electric shock at the communication interfaces.

- ▶ Connect only suitable devices to the bus system.

WARNING

Risk of injury due to incorrect installation

Dangerous situations may arise from unsafe or incorrect installation.

- ▶ Do not carry out your own conversions or modifications on the unit.
- ▶ Ensure the integration into an Emergency Off safety circuit.



Contact load for the accessory connections to "accessory"

1. Note the maximum contact load of 200 mA per connection.
2. However, do not exceed the total sum of the load of all connections of 450 mA.



Potential-free connections

- All inputs and outputs of the "remote," "Profibus," and "PV.can" connections are galvanically isolated from +U_B.
- The contacts of relays 1, 2 and 3 are potential-free.

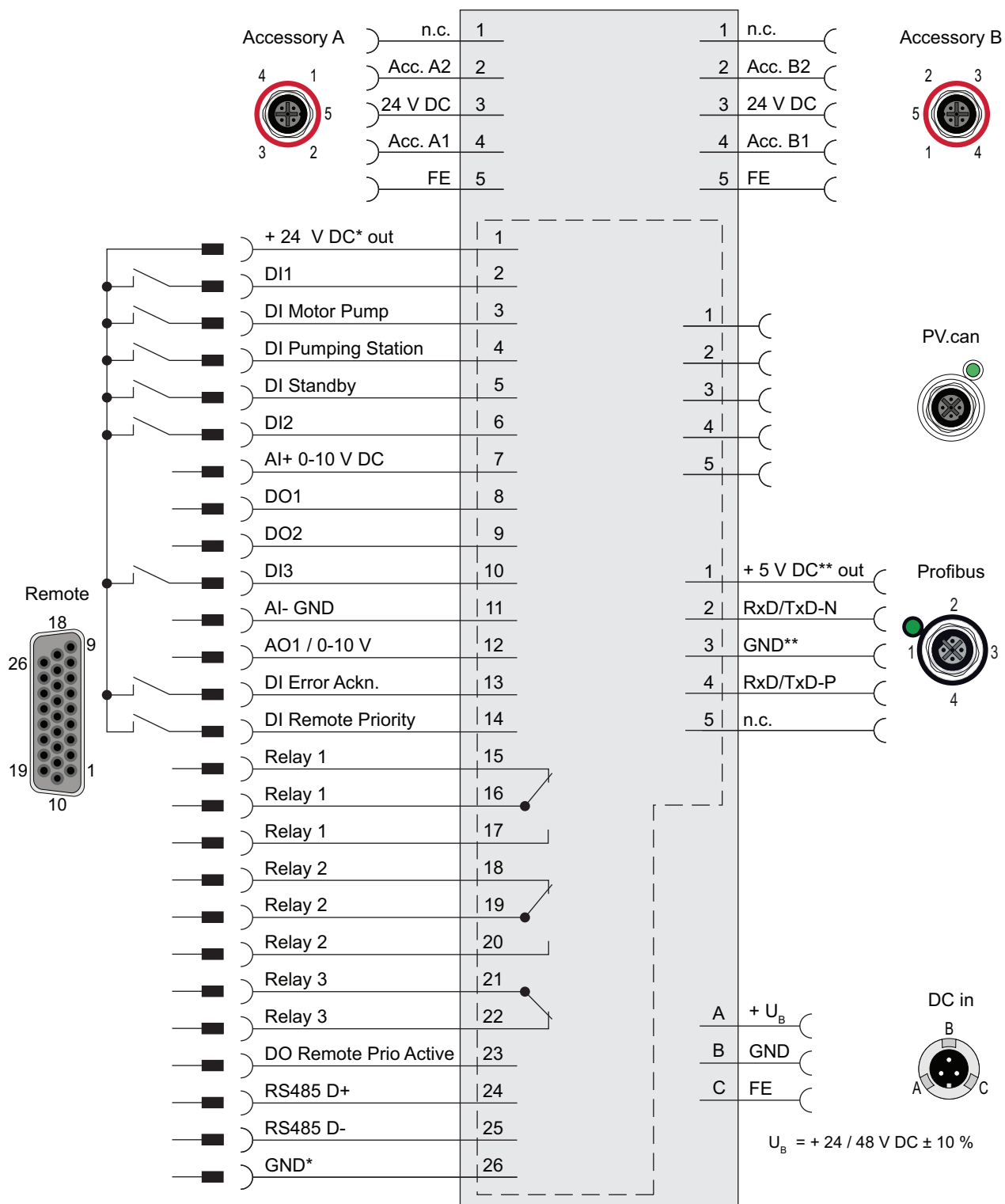
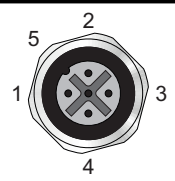


Fig. 2: Connection diagram for the electronic drive unit

4.2 "Profibus" connection

	Pin	Assignment
	1	+5 V DC
	2	RxD/TxD-N (received data and transmitted data, Line A)
	3	GND (for Pin 1)
	4	RxD/TxD-P (reception and transmission data, Line B)
	5	not connected

Tbl. 8: Terminal lay-out of "Profibus" M12 connection

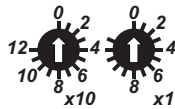


Fig. 3: Profibus address selector switch

Establishing a Profibus connection

1. Establish the Profibus connection in compliance with the applicable guidelines.
2. Use a suitable connection cable and components from the Pfeiffer Vacuum line of accessories.
3. Use a Profibus master to configure the Profibus interface with the GSD file included in the turbo-pump shipment.
4. Select a valid and unique Profibus address at the address selector switches in decimal coding from 1 to 125.
5. Avoid conflicts with the functions already available in module PPO1.
6. Fit the rubber plugs over the address selector switches straight and as deep as possible to achieve the stated protection class.
7. Restart the system by interrupting the supply voltage. This will validate the selected Profibus address.

4.3 Connection "remote"

The 26-pin sub-D connection with the "remote" designation offers the possibility to operate the electronic drive unit via remote control. The accessible individual functions are mapped to "PLC levels". The following specifications are the factory settings for the electronic drive unit. They can be configured with the Pfeiffer Vacuum parameter set.

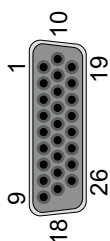
Required tools

- Calibrated torque wrench
- Hexagon socket wrench, **SW 4,5**

Connect remote control to "remote"

- ▶ Remove the remote plug from the electronic drive unit and connect a remote control.
- ▶ Use screened plugs and cables.
- ▶ Fasten the remote control to connector "remote".
 - Tightening torque on the spacer bolts of the sub-D socket: **0,25 - 0,3 Nm**

	Pin	Assignment	Description, factory setting
	1	+24 V DC* output (V+)	Reference voltage for all digital inputs and outputs
	2	DI1	Enable venting (open: off, V+: on)
	3	DI motor vacuum pump	Drive motor (open: off; V+: on)
	4	DI Pumping station	open: off; V+: on and malfunction acknowledgment
	5	DI Standby	Standby rotation speed (open: off, V+: on)
	6	DI2	Heater (open: off, V+: on)
	7	AI+ rotation speed setting mode	Setpoint in rotation speed setting mode; 2 - 10 V DC corresponds to 20 - 100% of the nominal rotation speed
	8	DO1	Speed-control switchpoint reached; GND: no, V+: yes ($I_{\max} = 50 \text{ mA}/24 \text{ V}$)
	9	DO2	GND: Fault, V+: no fault ($I_{\max} = 50 \text{ mA}/24 \text{ V}$)
	10	DI3	Sealing gas (open: off, V+: on)
	11	AI rotation speed setting mode GND	Setpoint in rotation speed setting mode; GND
	12	AO1	Actual speed; 0 to 10 V DC corresponds to 0 to 100%: $R_L > 10 \text{ k}\Omega$
	13	DI malfunction acknowledgment	Malfunction acknowledgement: V+ pulse (min. 500 ms)
	14	DI remote priority	Operation via "remote" interface (open: off, V+: set and takes priority over other digital inputs)
	15	Relay 1	Connection with pin 16, if relay 1 inactive
	16	Relay 1	Speed-control switchpoint reached; Relay contact 1 ($\text{rpm}_{\max} = 50 \text{ V DC}$; $I_{\max} = 1 \text{ A}$)
	17	Relay 1	Connection with pin 16, if relay 1 active
	18	Relay 2	Connection with pin 19, if relay 2 inactive
	19	Relay 2	No fault; relay contact 2 ($\text{rpm}_{\max} = 50 \text{ V DC}$; $I_{\max} = 1 \text{ A}$)
	20	Relay 2	Connection with pin 19, if relay 2 active
	21	Relay 3	Connection with pin 22, if relay 3 inactive
	22	Relay 3	Warning; relay contact 3 ($\text{rpm}_{\max} = 50 \text{ V DC}$; $I_{\max} = 1 \text{ A}$)
	23	DO remote priority	GND: off, V+: Remote priority active
	24	RS-485 D+	in accordance with the specification and Pfeiffer Vacuum protocol
	25	RS-485 D-	in accordance with the specification and Pfeiffer Vacuum protocol
	26	Earth (GND*)	Reference earth for all digital inputs and outputs



Tbl. 9: Terminal lay-out of 26-pin "remote" connection

5 Interfaces

5.1 Profibus interface

Use Profibus modules

- Use precisely one of the following modules in each case.

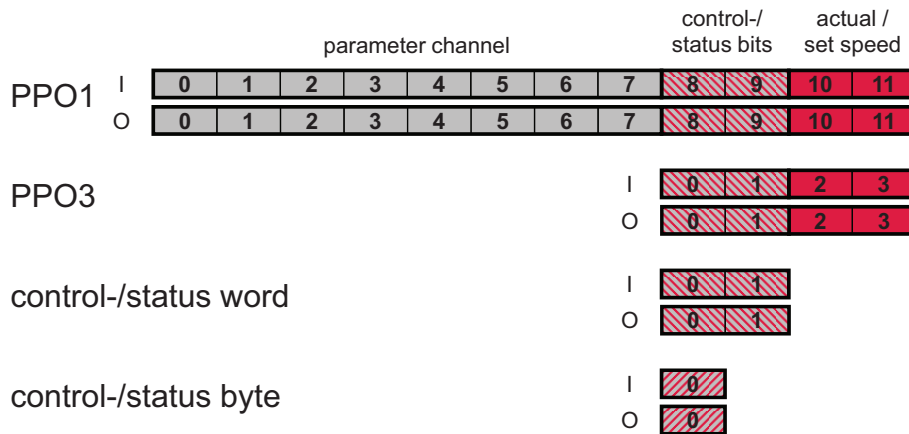


Fig. 4: Illustration of the Profibus modules

Module	Description	Input data (I) ²⁾	Output data (O) ³⁾
PPO1	Control/status bits, rotation speed set and actual value, noncyclical parameter access	12 byte	12 byte
PPO3	Control/status bits, rotation speed set and actual value	4 byte	4 byte
Control/status word	Control/status bits	2 byte	2 byte
Control/status byte		1 byte	1 byte

Tbl. 10: Overview of the Profibus modules

- The data format is always "high word/byte first" (Motorola).
- All Pfeiffer Vacuum parameters of the data type 0, 1, 2 and 7 can be used for parameter channel PPO1 and the parameterization data.
- Pfeiffer Vacuum parameters [P:303] and [P:360] to [P:369] provide additional error messages respective to their coding.
- Pfeiffer Vacuum parameter [P:349] provides the value 0xAC20D630.
- You can influence access to the functions in the modules via the electronic drive unit's external circuit (e.g. via "remote").

5.1.1 Assign parameterization data

Configuration requirement

- Once-only setting of a configuration which deviates from the delivery condition ("start-up configuration")
- The definition of actions in the "fail-safe" Profibus state
- In case of threshold monitoring (e.g. failure of the master) ("fail-safe action")

Predefined parameterization data

- All parameters are populated with default values.
- The protocol adds 8 bytes of parameterization data for each parameter.

2) Input data = Data communication electronic drive unit to master (e.g. PLC)

3) Output data = Data communication master (e.g. PLC) to electronic drive unit

Byte	Description
0, bit 7	0: Parameter for "start-up configuration" 1: Parameter for "fail-safe action"
0, bit 6	0: Parameter value is integer 1: Parameter value floating point (in accordance with IEEE 754)
2 to 3	Parameter number
4 to 7	Parameter value

Tb1. 11: Definitions of Profibus parameterization data

Procedure

1. Define up to 6 parameters for all modules as required.
2. Populate undefined positions with "0".

Designation	Example of module designation
Module without additional parameter	PPO1, PPO3, control/status word, control/status byte
Modules with 1 to 6 additional parameters	PPO1 (1 prm) to (6 prm) PPO3 (1 prm) to (6 prm) control/status word (1 prm) to (6 prm) control/status byte (1 prm) to (6 prm)

Tb1. 12: Profibus module designation in terms of parameterization data

5.1.2 Profibus module "PPO1"

Byte	Parameter channel						Control/status bits	Rotation speed
	0		1	2 – 3	4 – 7		8 – 9	10 – 11
Bit	7 – 4	3	2 – 0	7 – 0	7 – 0	7 – 0	7 – 0	7 – 0
O	Request	0	Parameter number	0	-		Control word	Target value in rotation speed setting mode (Hz)
I	Response				Parameter value		Status word	Actual rotational speed (Hz)

Tb1. 13: Output and input data ("PPO1")

Value	Description	Corresponding response
0	No request	0
1	Read parameter value	2 or 7 (for data type 0, 1 or 7) 7 or 11 (for data type 2)
3	Write parameter value as integer	2, 7 or 8
10	Write parameter value (data type 2 only) as a floating point value in accordance with IEEE 754	7, 8 or 11

Tb1. 14: Request (output data "PPO1")

Value	Description
0	No response
2	Transfer parameter value as integer
7	Request not executable, value contains error number
8	No operation possible via Profibus
11	Transfer parameter value as a floating point value in accordance with IEEE 754

Tb1. 15: Response (input data "PPO1")

Error number	Description
0	Invalid parameter number, function already used in control word
1	Parameter value not changeable
2	Below/above value range
5	Incorrect data type
101	Invalid request
102	Parameter value not readable
103	Invalid format

Tbl. 16: Error numbers (response "PPO1")

Bit	Output data (O)	Input data (I)
15	-	Reserved (do not evaluate)
14		
13		
12	Enable vents	0
11	Heating	Pump rotating
10	Enable process data (control word and parameter channel): 0 = ignore 1 = accept	Target speed reached
9	-	Process data enabled
8	Standby	Speed-control switch point reached
7	Error acknowledgement; -> automatic trip switch	Warning
6	Rotation speed setting mode	Automatic trip switch (switching back on only by pumping station off and back on)
5	-	1
4	-	
3	-	
2	-	Defect
1	-	Operation (no error, pumping station and motor pumps are on, no automatic trip switch)
0	Pump station	0
		Standby (no error, no start inhibit, release process data)

Tbl. 17: Control word/status word ("PPO1")

5.1.3 Profibus module "PPO3"

Byte	Control/status bits	Rotation speed
	0 – 1	2 – 3
O	Control word (see PPO1)	Target value in rotation speed setting mode (Hz)
I	Status word (see PPO1)	Actual rotational speed (Hz)

Tbl. 18: Output and input data ("PPO3")

5.1.4 Profibus module "control/status word"

Byte	Control/status bits
	0 – 1
O	Control word (see PPO1)
I	Status word (see PPO1)

Tbl. 19: Output and input data ("control/status word")

5.1.5 Profibus module "control/status byte"

Bit	Output data (O)	Input data (I)
7	Malfunction acknowledgment; -> Start inhibit (to restart the pumping station must be switched off and back on)	Warning, general
6	Standby	Warning, temperature
5	Enable venting	Operation (no error, pumping station and motor pump are on, no automatic trip switch)
4	Heating	Rotation speed switchpoint reached
3	-	Error
2	Enable process data (control byte): 0 = ignore 1 = accept	0
1	-	Pump rotating
0	Pumping station	Set rotation speed reached

Tbl. 20: Control word/status word ("control/status byte")

5.1.6 Expanded diagnostics data

Byte	Designation	Description
1 – 6	Profibus standard diagnostics	Defined by Profibus specification
7	Length of the external diagnostics data	
8 – 36		Reserved
37 – 38	Current error code	0: no error 1 – 999: Device error ⁴⁾ 1001 – 1999: Device warning 1 – 999 2000: unknown module 3xxx Parameterization data faulty as indicated by the error number in the parameter channel ⁵⁾
39 – 69	Internal state	



Tbl. 21: Profibus: Expanded diagnostics data


4) Device errors and warnings are available on the electronic drive unit

5) See PPO1

5.2 Pfeiffer Vacuum protocol for RS-485 interface

5.2.1 Telegram frame

The telegram frame of the Pfeiffer Vacuum protocol contains only ASCII code characters [32; 127], the exception being the end character of the telegram C_R . Basically, a host  (e.g. a PC) sends a telegram, which a device  (e.g. electronic drive unit or gauge) responds to.

a2	a1	a0	*	0	n2	n1	n0	l1	l0	dn	...	d0	c2	c1	c0	C_R
a2 – a0				Unit address for device 												
				<ul style="list-style-type: none"> Individual address of the unit ["001"; "255"] Group address "9xx" for all identical units (no response) Global address "000" for all units on the bus (no response) 												
*				Action according to telegram description												
n2 – n0				Pfeiffer Vacuum parameter numbers												
l1 – l0				Data length dn to d0												
dn – d0				Data in the respective data type (see chapter "Data types", page 25).												
c2 – c0				Checksum (sum of ASCII values of cells a2 to d0) modulo 256												
C_R				carriage return (ASCII 13)												

5.2.2 Telegram description

Data query  -->  ?

a2	a1	a0	0	0	n2	n1	n0	0	2	=	?	c2	c1	c0	C_R
----	----	----	---	---	----	----	----	---	---	---	---	----	----	----	-------

Control command  -->  !

a2	a1	a0	1	0	n2	n1	n0	l1	l0	dn	...	d0	c2	c1	c0	C_R
----	----	----	---	---	----	----	----	----	----	----	-----	----	----	----	----	-------

Data response / Control command understood  --> 

a2	a1	a0	1	0	n2	n1	n0	l1	l0	dn	...	d0	c2	c1	c0	C_R
----	----	----	---	---	----	----	----	----	----	----	-----	----	----	----	----	-------

Error message  --> 



a2	a1	a0	1	0	n2	n1	n0	0	6	N	O	_	D	E	F	c2	c1	c0	C_R
										_	R	A	N	G	E				
										_	L	O	G	I	C				

NO_DEF Parameter number n2–n0 no longer exists
 _RANGE Data dn–d0 outside the permissible range
 _LOGIC Logical access error

5.2.3 Telegram example 1



Data query

Current rotation speed (parameter [P:309], device address: "123")

 -->  ?	1	2	3	0	0	3	0	9	0	2	=	?	1	1	2	C_R
ASCII	49	50	51	48	48	51	48	57	48	50	61	63	49	49	50	13

Data response: 633 Hz



Current rotation speed (parameter [P:309], device address: "123")

 --> 	1	2	3	1	0	3	0	9	0	6	0	0	0	6	3	3	0	3	7	C_R
ASCII	49	50	51	49	48	51	48	57	48	54	48	48	48	54	51	51	48	51	55	13

5.2.4 Telegram example 2



Control command

Switch on the pumping station (parameter **[P:010]**, device address: "042")

 -->  !	0	4	2	1	0	0	1	0	0	6	1	1	1	1	1	1	0	2	0	C _R
ASCII	48	52	50	49	48	48	49	48	48	54	49	49	49	49	49	49	48	50	48	13

Control command understood

Switch on the pumping station (parameter **[P:010]**, device address: "042")

 --> 	0	4	2	1	0	0	1	0	0	6	1	1	1	1	1	1	0	2	0	C _R
ASCII	48	52	50	49	48	48	49	48	48	54	49	49	49	49	49	49	48	50	48	13

5.2.5 Data types

No.	Data type	Description	Length l1 – l0	Example
0	boolean_old	Logical value (false/true)	06	000000 is equivalent to false 111111 is equivalent to true
1	u_integer	Positive whole number	06	000000 to 999999
2	u_real	Positive fixed point number	06	001571 corresponds with 15.71
4	string	Any character string with 6 characters. ASCII codes between 32 and 127	06	TC_110, TM_700
6	boolean_new	Logical value (false/true)	01	0 is equivalent to false 1 is equivalent to true
7	u_short_int	Positive whole number	03	000 to 999
10	u_expo_new	Positive exponential number. The last of both digits are the exponent with a deduction of 20.	06	100023 is equivalent to $1,0 \cdot 10^3$ 100000 is equivalent to $1,0 \cdot 10^{-20}$
11	string16	Any character string with 16 characters. ASCII codes between 32 and 127	16	BrezelBier&Wurst
12	string8	Any character string with 8 characters. ASCII codes between 32 and 127	08	Example

6 Parameter set

6.1 General

Important settings and function-related characteristics are factory-programmed into the electronic drive unit as parameters. Each parameter has a three-digit number and a description. The parameter can be accessed via Pfeiffer Vacuum control units or externally via RS-485 using Pfeiffer Vacuum protocol.

The vacuum pump starts in standard mode with factory default pre-set parameters.



Non-volatile data storage










When switching off or in the event of unintentional voltage drop, the **parameters** and the operating hours stay saved in the electronics.













#	Three digit number of the parameter
Indicator	Display of parameter description
Description	Brief description of the parameters
Functions	Function description of the parameters
Data type	Type of formatting of the parameter for the use with the Pfeiffer Vacuum protocol
Access type	R (read): Read access; W (write): Write access
Unit	Physical unit of the described variable
min. / max.	Permissible limit values for the entry of a value
default	Factory default pre-setting (partially pump-specific)
	The parameter can be saved persistently in the electronic drive unit







Tbl. 22: Explanation and meaning of the parameters

6.2 Control commands

#	Display	Description	Functions	Data type	Access type	Unit	min.	max.	default	
001	Heating	Heating	0 = off 1 = on	0	RW		0	1	0	✓
002	Standby	Standby	0 = off 1 = on	0	RW		0	1	0	✓
004	RUTimeCtrl	Run-up time monitoring	0 = off 1 = on	0	RW		0	1	1	✓
009	ErrorAckn	Malfunction acknowledgement	1 = Malfunction acknowledgement	0	W		1	1		
010	PumpgStatn	Pumping station	0 = off 1 = on and malfunction acknowledgement	0	RW		0	1	0	✓
012	EnableVent	Enable venting	0 = no 1 = yes	0	RW		0	1	0	✓
017	CfgSpdSwPt	Rotation speed switchpoint configuration	0 = Rotation speed switchpoint 1 1 = Rotation speed switchpoints 1 & 2	7	RW		0	1	0	✓




#	Display	Description	Functions	Data type	Access type	Unit	min.	max.	default	
019	Cfg DO2	Output DO2 configuration	0 = Rotation speed switchpoint reached 1 = No error 2 = Error 3 = Warning 4 = Error and/or warning 5 = Set rotation speed reached 6 = Pump on 7 = Pump accelerating 8 = Pump decelerating 9 = Always "0" 10 = Always "1" 11 = Remote priority active 12 = Heating 13 = Backing pump 14 = Sealing gas 15 = Pumping station 16 = Pump rotating 17 = Pump has stopped 19 = Pressure switch point 1 not reached 20 = Pressure switch point 2 not reached 21 = Fore-vacuum valve, delayed 22 = Backing pump stand-by	7	RW		0	22	1	
023	MotorPump	Motor pump	0 = off 1 = on	0	RW		0	1	0	
024	Cfg DO1	Output DO1 configuration	Settings, see [P:019]	7	RW		0	22	0	
025	OpMode BKP	Backup pump operating mode	0 = continuous operation 1 = intermittent operation 2 = Delayed switching on	7	RW		0	2	0	
026	SpdSetMode	Rotation speed setting mode	0 = off 1 = on	7	RW		0	1	0	
027	GasMode	Gas mode	0 = heavy gases 1 = light gases 2 = Helium	7	RW		0	2	0	
028	Cfg Remote	Remote configuration	0 = Standard 4 = Relay, inverted	7	RW		0	4	0	
030	VentMode	Venting mode	0 = delayed venting 1 = no venting 2 = direct venting	7	RW		0	2	0	


#	Display	Description	Functions	Data type	Access type	Unit	min.	max.	default	
035	Cfg Acc A1	Configuration accessory connection A1	0 = fan (continuous operation) 1 = Venting valve, closed without current 2 = Heater 3 = Backing pump 4 = Fan (temperature controlled) 5 = Sealing gas 6 = Always "0" 7 = Always "1" 8 = Power failure venting unit 12 = Second venting valve 13 = Sealing gas monitoring 14 = Heating (lower part temperature controlled)	7	RW		0	14	0	
036	Cfg Acc B1	Configuration accessory connection B1	Options, see [P:035]	7	RW		0	14	1	
037	Cfg Acc A2	Configuration accessory connection A2	Options, see [P:035]	7	RW		0	14	3	
038	Cfg Acc B2	Configuration accessory connection B2	Options, see [P:035]	7	RW		0	14	2	
041	Press1HVen	Release HV sensor integrated (only IKT)	0 = off 1 = on 2 = On, with rotation speed switch point reached 3 = On, with pressure switch point not reached	7	RW		0	3	2	
045	Cfg Rel R1	Configuration, relay 1	Options, see [P:019]	7	RW		0	22	0	
046	Cfg Rel R2	Configuration, relay 2	Options, see [P:019]	7	RW		0	22	1	
047	Cfg Rel R3	Configuration, relay 3	Options, see [P:019]	7	RW		0	22	3	
050	SealingGas	Sealing gas	0 = off 1 = on	0	RW		0	1	0	
055	Cfg AO1	Output AO1 configuration	0 = actual speed 1 = output 2 = current 3 = Always 0 V 4 = Always 10 V 5 = Follows AI1 6 = Pressure value 1 7 = Pressure value 2 8 = Fore-vacuum control	7	RW		0	8	0	
057	Cfg AI1	Configuration input AI1	0 = Switched off 1 = Setpoint in rotation speed setting mode	7	RW		0	1	0	

#	Display	Description	Functions	Data type	Access type	Unit	min.	max.	de-fault	
060	CtrlVialnt	Operate via interface	1 = remote 2 = RS-485 4 = PV.can 8 = Fieldbus 16 = E74 255 = Unlock interface selection	7	RW		1	255	1	
061	IntSelLckd	Interface selection locked	0 = off 1 = on	0	RW		0	1	0	
062	Cfg DI1	Configuration input DI1	Setting ≠ [P:063/064] 0 = Deactivated 1 = Enable vents 2 = Heater 3 = Sealing gas 4 = Run-up time monitoring 5 = Rotation speed setting mode 7 = Enable HV sensor	7	RW		0	7	1	
063	Cfg DI2	Configuration input DI2	Options, see [P:062] Setting ≠ [P:062/064]	7	RW		0	7	2	
064	Cfg DI3	Configuration input DI3	Options, see [P:062] Setting ≠ [P:062/063]	7	RW		0	7	3	

Tbl. 23: Control commands


6.3 Status requests

#	Display	Description	Functions	Data type	Access type	Unit	min.	max.	de-fault	
300	RemotePrio	Remote priority	0 = no 1 = yes	0	R		0	1		
302	SpdSwPtAtt	Rotation speed switchpoint reached	0 = no 1 = yes	0	R		0	1		
303	Error code	Error code		4	R					
304	OvTempElec	Excess temperature drive electronics	0 = no 1 = yes	0	R		0	1		
305	OvTempPump	Excess temperature pump	0 = no 1 = yes	0	R		0	1		
306	SetSpdAtt	Set rotation speed reached	0 = no 1 = yes	0	R		0	1		
307	PumpAccel	Pump accelerating	0 = no 1 = yes	0	R		0	1		
308	SetRotSpd	Set rotation speed (Hz)		1	R	Hz	0	999999		
309	ActualSpd	Actual rotational speed (Hz)		1	R	Hz	0	999999		
310	DrvCurrent	Drive current		2	R	A	0	9999.99		
311	OpHrsPump	Pump operating hours		1	R	h	0	65535		
312	Fw version	Drive electronics software version		4	R					
313	DrvVoltage	Drive voltage		2	R	V	0	9999.99		
314	OpHrsElec	Drive electronics operating hours		1	R	h	0	65535		

#	Display	Description	Func-tions	Data type	Access type	Unit	min.	max.	de-fault	
315	Nominal Spd	Nominal rotation speed (Hz)		1	R	Hz	0	999999		
316	DrvPower	Drive power		1	R	W	0	999999		
319	PumpCycles	Pump cycles		1	R		0	65535		✓
324	TempPwrStg	Final stage temperature		1	R	°C	0	999999		
326	TempElec	Electronics temperature		1	R	°C	0	999999		
330	TempPmpBot	Pump lower part temperature		1	R	°C	0	999999		
336	AccelDecel	Acceleration/deceleration		1	R	rpm/s	0	999999		
337	SealGasFlw	Sealing gas flow		1	R	sccm	0	999999		
342	TempBearng	Bearing temperature		1	R	°C	0	999999		
346	TempMotor	Motor temperature		1	R	°C	0	999999		
349	ElecName	Electronic drive unit designation		4	R					
354	HW Version	Hardware version drive electronics		4	R					
360	ErrHist1	Error code history, item 1		4	R					✓
361	ErrHist2	Error code history, item 2		4	R					✓
362	ErrHist3	Error code history, item 3		4	R					✓
363	ErrHist4	Error code history, item 4		4	R					✓
364	ErrHist5	Error code history, item 5		4	R					✓
365	ErrHist6	Error code history, item 6		4	R					✓
366	ErrHist7	Error code history, item 7		4	R					✓
367	ErrHist8	Error code history, item 8		4	R					✓
368	ErrHist9	Error code history, item 9		4	R					✓
369	ErrHist10	Error code history, item 10		4	R					✓
397	SetRotSpd	Set rotation speed (rpm)		1	R	rpm	0	999999		
398	ActualSpd	Actual speed (rpm)		1	R	rpm	0	999999		
399	NominalSpd	Nominal rotation speed (rpm)		1	R	rpm	0	999999		

Tbl. 24: Status requests

6.4 Set value settings

#	Display	Description	Func-tions	Data type	Access type	Unit	min.	max.	default	
700	RUTimeSVal	Set value run-up time		1	RW	min	1	120	8	✓
701	SpdSwPt1	Rotation speed switch point 1		1	RW	%	50	97	80	✓
707	SpdSVal	Set value in rotation speed setting mode		2	RW	%	20	100	65	✓
708	PwrSVal	Set value power consumption		7	RW	%	10	100	100 ⁶⁾	✓
710	Swoff BKP	Backing pump switch-off threshold for interval operation		1	RW	W	0	1000	0	✓
711	SwOn BKP	Backing pump switch-on threshold for interval operation		1	RW	W	0	1000	0	✓
717	StdbysVal	Set value rotation speed at standby		2	RW	%	20	100	66.7	✓

6) Depending on the pump type

#	Display	Description	Functions	Data type	Access type	Unit	min.	max.	default	
719	SpdSwPt2	Rotation speed switch point 2		1	RW	%	5	97	20	✓
720	VentSpd	Venting rotation speed at delayed venting		7	RW	%	40	98	50	✓
721	VentTime	Venting time at delayed venting		1	RW	d	6	3600	3600	✓
730	PrsSwPt 1	Pressure switch point 1		10	RW	hPa				✓
732	PrsSwPt 2	Pressure switch point 2		10	RW	hPa				✓
739	PrsSn1Name	Name sensor 1		4	R					
740	Pressure 1	Pressure value 1		10	RW	hPa				✓
742	PrsCorrPi 1	Correction factor 1		2	RW					✓
749	PrsSn2Name	Name sensor 2		4	R					
750	Pressure 2	Pressure value 2		10	RW	hPa				✓
752	PrsCorrPi 2	Correction factor 2		2	RW					✓
777	NomSpdConf	Nominal rotation speed confirmation		1	RW	Hz	0	1500	0	✓
791	SlgWrnThrs	Sealing gas flow warning threshold		1	RW	sccm	5	200	15	✓
797	RS485Adr	RS-485 interface address		1	RW		1	255	1	✓

Tbl. 25: Set value settings

6.5 Additional parameters for Profibus

#	Display	Description	Functions	Data type	Access type	Unit	min.	max.	default	
918		Profibus device address		1	R		1	125		
947		Error number		1	R		0	65535		
967		Control word (CW)		1	R		0	65535		
968		Status word (SW)		1	R		0	65535		

Tbl. 26: Parameters for Profibus connection

6.6 Additional parameters for the control unit




Additional parameters in the control unit

The basic parameter set is set in the electronic drive unit ex-factory. For controlling connected external components (e.g. vacuum measuring equipment), additional parameters (extended parameter set) are available in the corresponding Pfeiffer Vacuum control units.

- Refer to the corresponding operating instructions of the respective components.
- Select the extended parameter set with parameter **[P:794] = 1**.

#	Indicator	Description	Functions	Data type	Access type	Unit	min.	max.	default	
340	Pressure	Actual pressure value (ActiveLine)		7	R	hPa	$1 \cdot 10^{-10}$	$1 \cdot 10^3$		
350	Ctr Name	Control unit type		4	R					
351	Ctr Software	Control unit software version		4	R					
738	Gauge type	Type of pressure gauge		4	RW					

Parameter set

#	Indicator	Description	Functions	Data type	Access type	Unit	min.	max.	de- fault	
794	Param set	Parameter set	0 = Basic parameter set 1 = Extended parameter set	7	RW		0	1	0	
795	Servicelin	Insert service line		7	RW				795	

Tbl. 27: Parameters for control unit functions

7 Operation

7.1 Configuring the connections with the Pfeiffer Vacuum parameter set

The electronic drive unit is pre-configured with the factory default basic functions and is ready for operation. For individual requirements, you can configure most connections for the electronic drive unit with the parameter set.

7.1.1 Configure the "remote" connection

In the description, "active" signifies:

- for all digital outputs: V+ active high
- for all relays: contact changeover in accordance with the settings [P:028]

Option	Description
0 = Rotation speed switchpoint reached	active, once the switch-point is reached
1 = No error	active, with trouble-free operation
2 = Error	active, if the error message is active
3 = Warning	active, if a warning message is active
4 = Error and/or warning	active, if an error and/or warning is active
5 = Set rotation speed reached	active, once the set rotation speed switch-point is reached
6 = Pump on	active, if pumping station on, motor on and no error
7 = Pump accelerating	active, if pumping station on, current rotation speed < set rotation speed
8 = Pump decelerating	active, if pumping station on, current rotation speed > set rotation speed pumping station off, rotation speed > 3 Hz
9 = always 0	GND for the control of an external device
10 = always 1	+24 V DC for the control of an external device
11 = Remote priority active	active, if the remote priority is active
12 = Heating	Control corresponds to parameter [P:001]
13 = Backing pump	Control corresponds to parameter [P:010] and [P:025]
14 = Sealing gas	Control corresponds to parameter [P:050]
15 = Pumping station	Control corresponds to parameter [P:010]
16 = Pump rotating	active, if rotation speed > 1 Hz
17 = Pump has stopped	active, if rotation speed < 2 Hz
18 = TMS steady state ⁷⁾	active, if TMS set temperature stabilized
19 = Pressure switch point 1 not reached	Control corresponds to parameter [P:730] ([P:740] < [P:730])
20 = Pressure switch point 2 not reached	Control corresponds to parameter [P:732] ([P:750] < [P:732])
21 = Fore-vacuum valve, delayed	+24 V DC time-delayed after pumping station on
22 = Backing pump stand-by	Control of backing pump standby mode

Tbl. 28: Configure digital outputs and relays [P:019] and [P:024], or [P:045], [P:046], [P:047] and [P:028]

Option	Description
0 = Deactivated	Connection not operational
1 = Enable venting	Control corresponds to parameter [P:012]
2 = Heating	Control corresponds to parameter [P:001]
3 = Sealing gas	Control corresponds to parameter [P:050]

7) Only when using pumps with a temperature management system (TMS)

Option	Description
4 = Run-up time monitoring	Control corresponds to parameter [P:004]
5 = Rotation speed setting mode	Control corresponds to parameter [P:026]
7 = Enable HV sensor	Control corresponds to parameter [P:041] (0 or 1 only)

Tbl. 29: Configure digital inputs [P:062], [P:063] and [P:064]

Option	Description
0 = actual speed	Rotation speed signal; $0 - 10 \text{ VDC} = 0 - 100\% \times f_{\text{nominal}}$
1 = output	Output signal; $0 - 10 \text{ VDC} = 0 - 100\% \times P_{\text{max}}$
2 = current	Current signal; $0 - 10 \text{ VDC} = 0 - 100\% \times I_{\text{max}}$
3 = Always 0 V	Always GND
4 = Always 10 V	Output of permanent 10 V DC
5 = Follows AI1	Follows analog input 1
6 = Pressure value 1	Pressure value signal 0 V: Error 1 V: Not reached $1.5 - 8.5 \text{ V for sensor RPT } p \text{ (hPa)} = 10^{(U-5.5 \text{ V})}$ $1.5 - 8.5 \text{ V for sensor IKT } p \text{ (hPa)} = 10^{(U-10.5 \text{ V})}$ 9 V: Exceeded
7 = Pressure value 2	
8 = Fore-vacuum control	
	Fore-vacuum side; Control of Pfeiffer Vacuum turbo pumping stations

Tbl. 30: Configure analog output [P:055]

Option	Description
0 = Switched off	Connection not operational
1 = Setpoint in rotation speed setting mode	Rotation speed setting mode via pin 7 (0 – 10 V) and pin 11 (GND)

Tbl. 31: Configure analog input [P:057]**Procedure**

1. Set the digital outputs and relays via the parameters **[P:019]** and **[P:024]**, or **[P:045]**, **[P:046]**, **[P:047]** and **[P:028]**.
2. Set the digital inputs via the parameters **[P:062]**, **[P:063]** or **[P:064]**.
3. Set the analog output via parameter **[P:055]**.
4. Set the analog input via parameter **[P:057]**.

7.1.2 Configure accessory connections**Auxiliary connection to electronic drive unit TC 400 and TM 700**

The electronic drive unit of the turbopump offers space for the connection of maximum 4 accessory devices. M12 connector sockets with the designation "accessory" are available for this purpose.

- The accessory connections have been preconfigured at the factory.
- After connecting pre-configured accessory devices, these are immediately ready for operation according to the factory settings.
- The use of other accessories for turbopumps is possible and requires settings in the configuration of the electronic drive unit.
- The desired accessory output is configured via RS-485 using Pfeiffer Vacuum control units or a PC.
- For detailed information see the "Electronic drive unit TC 400" or "Electronic drive unit TC 700" operating instructions.

Option	Description
0 = fan (continuous operation)	Control via pumping station parameters
1 = Venting valve, closed without current	Control via parameter Enable venting. When using a venting valve closed without current
2 = Heating	Control via heating and speed switch point reached parameters
3 = Backing pump	Control via parameter Pumping station and backing pump operating mode
4 = Fan (temperature controlled)	Control via parameter Pumping station and temperature threshold value
5 = Sealing gas	Control via parameter Pumping station and sealing gas
6 = Always "0"	GND for the control of an external device
7 = Always "1"	+24 V DC for the control of an external device
8 = Power failure venting unit	Control via parameter Enable venting. When using a power failure venting unit
9 = TMS Heating ⁸⁾	Control via TMS switchbox
10 = TMS Cooling ⁹⁾	Control of the cooling water supply TMS
12 = Second venting valve	Control via parameter Enable venting and falling below 50% of the nominal rotation speed. When using a venting valve closed without current.
13 = Sealing gas monitoring	Control via parameter Pumping station and sealing gas
14 = Heating (lower part temperature controlled)	Control of the heating. Control via lower part heating parameters

Tbl. 32: Accessory connections

Procedure

- Carry out the configuration of the connections via parameter **[P:035]**, **[P:036]**, **[P:037]** or **[P:038]**.

7.1.3 Select interfaces

The option "Control via Interface" serves the display of the interface currently active in the electronic drive unit. The communication interfaces thus automatically achieve control priority.

Option	Description
1 = remote	Operation via connection "remote"
2 = RS-485	Operation via connection "RS-485"
4 = PV.can	For service purposes only
8 = Fieldbus	Operation via fieldbus
16 = E74	Operation via connection "E74"

Tbl. 33: Parameter [P:060]

Option	Description
0 = off	Interface selection can be set via parameter [P:060] .
1 = on	Interface selection locked

Tbl. 34: Parameter [P:061]

8) Only when using pumps with a temperature management system (TMS)

9) Only when using pumps with a temperature management system (TMS)

7.2 Operating modes

7.2.1 Gas type-dependent operation

NOTICE

Turbopump destruction due to gases with too high molecular masses

The pumping of gases with impermissible high molecular masses leads to the destruction of the turbopump.

- Make sure that the gas mode is set correctly by **[P:027]** in the electronic drive unit.
- Consult Pfeiffer Vacuum before you use gases with higher molecular masses (> 80).

High gas throughput and high rotation speed lead to strong friction heating of the rotor. To avoid overheating, power to rotation speed characteristics are implemented in the electronic drive unit. The power characteristic enables the operation of the turbopump at any rotation speed with the maximum permissible gas throughput without thermally overloading the turbopump. The maximum power consumption depends on the gas type. 3 characteristics are available for the parameterization in order to completely exhaust the turbopump's capacity for each gas type.

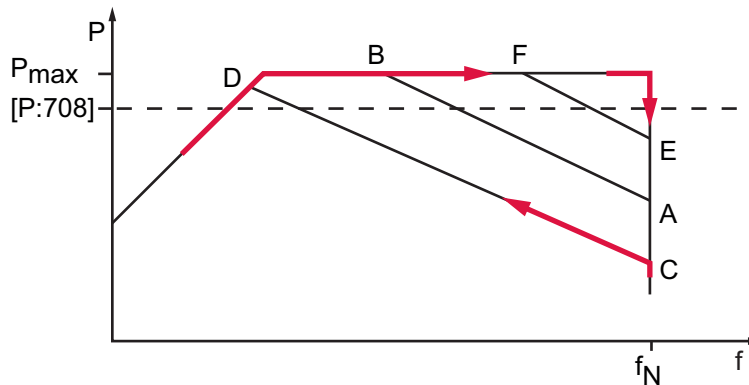


Fig. 5: Schematic diagram of power characteristics, example of heavy gases **[P:027] = 0**

P	Power consumption	C-D	Power characteristic in gas mode "0" (gases with molecular mass > 39 , e.g. Argon)
f	Rotation speed	A-B	Power characteristic in gas mode "1" (gases with molecular mass ≤ 39)
P_{\max}	Maximum power consumption	E-F	Power characteristic in gas mode "2" (Helium)
f_N	Nominal rotation speed		

Setting gas mode

1. Check the current gas mode set with parameter **[P:027]**.
2. Set the parameter **[P:027]** to the required value.
3. If necessary, set a lower frequency in rotation speed setting mode in order to avoid rotation speed fluctuations.

The turbopump runs up with maximum power consumption. When the nominal and/or set rotation speed is reached, the electronic drive unit automatically switches over to the chosen power characteristic of the selected gas mode. The increase in the power consumption initially compensates an increasing gas throughput to keep the rotation speed of the turbopump constant. The turbopump heats up higher due to the increasing gas friction. When the gas-type-dependent maximum power is exceeded, the rotation speed of the turbopump is reduced by the electronic drive unit until a permissible balance between power and gas friction is achieved.

7.2.2 Set value power consumption

Set parameter **[P:708]**

When setting the specified power consumption below 100%, the run-up time is extended.

1. Set the parameter **[P:708]** to the required value in %.
2. Where necessary, adjust the parameter **[P:700] RUTimeSVal** to avoid error messages when starting up.

7.2.3 Run-up time

The turbopump run-up is time-monitored ex-factory. There are various causes of prolonged run-up times, for example:

- Excessive gas throughput
- Leak in system
- Setpoint of the run-up time too low

Set parameter [P:700]

1. Where applicable, eliminate any external and application-related causes.
2. Adjust the run-up time with parameter [P:700].

7.2.4 Rotation speed switch points

You can use the rotation speed switch point for the "turbopump operational for the process" message. Exceeding or underrunning the active rotation speed switch point activates a signal at the pre-configured output on the electronic drive unit and at the status parameter [P:302].

Rotation speed switch point 1

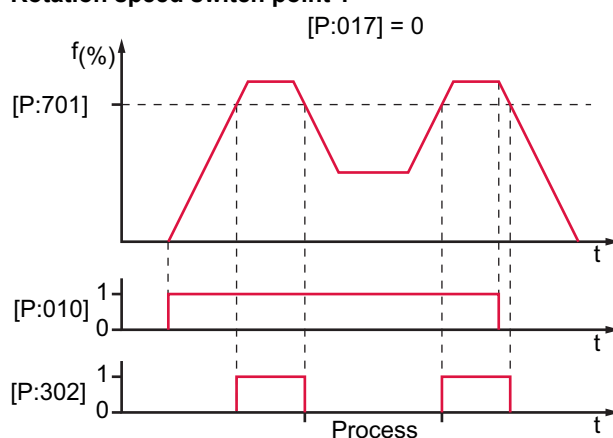


Fig. 6: Rotation speed switch point 1 active

Adjusting rotation speed switch point 1

Signal output and status parameters are based on the set value for the rotation speed switch point 1 [P:701].

1. Set the parameter [P:701] to the required value in %.
2. Set the parameter [P:017] to "0".

Rotation speed switch points 1 & 2

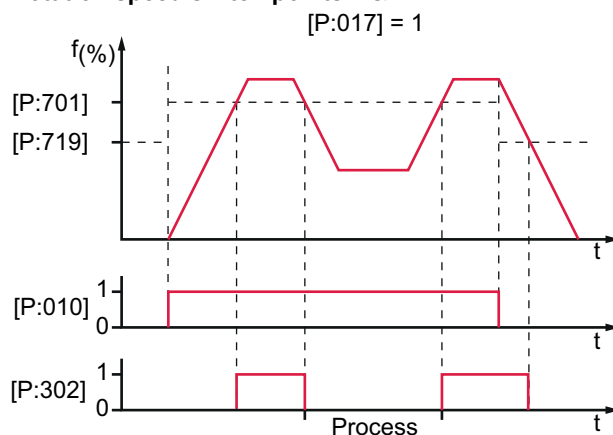


Fig. 7: Rotation speed switch points 1 & 2 active, [P:701] > [P:719]

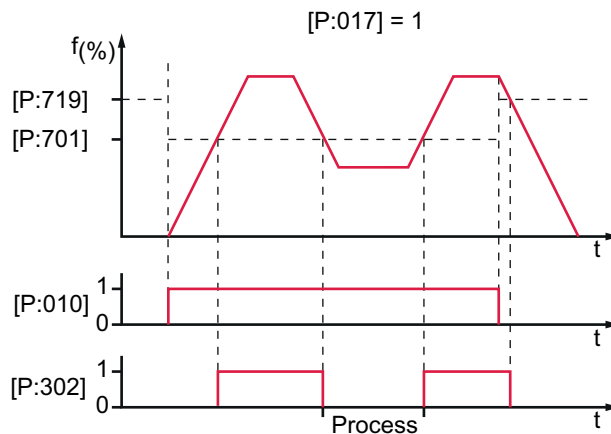


Fig. 8: Rotation speed switch points 1 & 2 active, [P:701] < [P:719]

Setting the rotation speed switch points 1 & 2

1. Set the parameter **[P:701]** to the required value in %.
2. Set the parameter **[P:719]** to the required value in %.
3. Set the parameter **[P:017]** to "1".

When the pumping station **[P:010]** is switched on, rotation speed switch point 1 is the signal generator. When the pumping station is switched off, the signal output and status request orientate at rotation speed switch point 2. The signal output is subject to the hysteresis between both switchpoints.

7.2.5 Rotation speed setting mode

The rotation speed setting mode reduces the speed and hence the pumping speed of the turbopump. The pumping speed of the turbopump changes proportional to its rotation speed. Standby mode is ineffective during rotation speed setting mode. The set value in rotation speed setting mode **[P:707]** sets the set rotation speed. The rotation speed switch point varies with the set rotation speed. Underrunning or exceeding the set value in rotation speed setting mode activates or deactivates the status signal **[P:306] SetSpdAtt**.



Permissible variable rotation speed

Values in the rotation speed setting mode or standby mode are subject to the permissible rotation speed range of the respective vacuum pump (technical data). Underrunning the minimum permissible value leads to the warning message **Wrn100**. The electronic drive unit automatically adjusts the set rotation speed to the next valid value.

Set the rotation speed setting mode

1. Set the parameter **[P:707]** to the required value in %.
2. Set the parameter **[P:026]** to "1".
3. Check the set rotation speed (parameter **[P:308]** or **[P:397]**).

7.2.6 Standby

Pfeiffer Vacuum recommends standby mode for the turbopump during process and production stops. When standby mode is active, the electronic drive unit reduces the rotation speed of the turbo pump. Standby mode is ineffective during rotation speed setting mode. The factory setting for stand-by mode is 66.7 % of the nominal rotation speed. Underrunning or exceeding the set value in standby mode activates or deactivates the status signal **[P:306] SetSpdAtt**.



Permissible variable rotation speed

Values in the rotation speed setting mode or standby mode are subject to the permissible rotation speed range of the respective vacuum pump (technical data). Underrunning the minimum permissible value leads to the warning message **Wrn100**. The electronic drive unit automatically adjusts the set rotation speed to the next valid value.

Setting the related parameters

1. Set the parameter **[P:717]** to the required value in %.
2. Set the parameter **[P:026]** to "0".
3. Set the parameter **[P:002]** to "1".
4. Check the set rotation speed (parameter **[P:308]** or **[P:397]**).

7.2.7 Confirming speed specification

The typical nominal rotation speed of a turbopump is preset ex factory in the electronic drive unit. If the electronic drive unit is replaced or a different pump type is used, the set value settings of the nominal rotation speed is cleared. The manual confirmation of the nominal rotation speed is part of a redundant safety system as a measure for preventing excess rotation speed.

HiPace	Confirmation of nominal rotation speed [P:777]
300	1000 Hz
400 / 700 / 800	820 Hz

Tbl. 35: Characteristic nominal rotation speeds of the turbopumps**Required aids**

- A connected Pfeiffer Vacuum control unit.
- Knowledge of the configuration and setting of electronic drive unit operating parameters.

Set parameter [P:777]

- Set the parameter **[P:777]** according to the pump type.

Once the nominal rotation speed is reached, the turbopump will run at idle without additional gas throughput. Depending on process or application requirements, the nominal rotation speed can be reduced in rotation speed setting mode or stand-by mode.

7.2.8 Backing pump operating modes

Operation of a connected backing pump via the electronic drive unit depends on the backing pump type.

Operating mode [P:025]	Recommended booster pump
"0" Continuous operation	All backing pumps
"1" Interval mode	Diaphragm pumps only
"2" Delayed switching on	All backing pumps
"3" Delayed interval mode	Diaphragm pumps only

Tbl. 36: Backing pump operating modes**Setting continuous operation**

With "pumping station on", the electronic drive unit sends a signal to the configured accessory connection to switch on the backing pump.

1. Set the parameter **[P:025]** to "0".
2. Use this signal for the control of a fore-vacuum safety valve.

Set interval operation and determine the switching threshold

Interval operation extends the service life of the diaphragm of a connected diaphragm pump. Either a diaphragm pump with a built-in semiconductor relay or an interconnected relay box with a semiconductor relay is required for interval operation. The electronic drive unit switches the backing pump on or off depending on the power consumption of the turbopump. A relationship to the fore-vacuum pressure results from the power consumption. The backing pump operating mode offers adjustable switch-on and switch-off thresholds. Fluctuations in the power consumption of idling turbopumps and varying fore-vacuum pressures of the backing pumps require individual settings of the interval operation.

Pfeiffer Vacuum recommends interval operation between 5 and 10 hPa. A pressure gauge and a dosing valve are required to set the switching thresholds.

1. Set the parameter **[P:025]** to "1".
2. Switch on the vacuum system with the parameter **[P:010]** ("pumping station").
3. Wait for the run-up.

4. Allow the gas to run via the dosing valve and set the fore-vacuum pressure to 10 hPa.
5. Read the drive power at parameter **[P:316]** and note the value.
6. Set the switch-on threshold of the backing pump with parameter **[P:711]** to the determined drive power for a 10 hPa fore-vacuum pressure.
7. Reduce the fore-vacuum pressure to 5 hPa.
8. Read the drive power at parameter **[P:316]** and note the value.
9. Set the switch-off threshold of the backing pump with parameter **[P:710]** to the determined drive power for a 5 hPa fore-vacuum pressure.

Delayed switching on

Simultaneous switching on of the backing pump and turbopump may cause undesired gas flow. To avoid this, depending on the process or application requirements, you can operate the backing pump with a delayed switch-on. The delayed switch-on depends on the rotation speed of the turbopump. The delayed switch-on has a fixed value of 360 rpm in the electronic drive unit.

- Switch-off threshold, parameter **[P:710]**
 - Switch-on threshold, parameter **[P:711]**
 - Delay 8 s.
1. Set the parameter **[P:025]** to "2".
 2. Use this signal for the control of a fore-vacuum safety valve.

Delayed interval operation

Fluctuations during the interval operation may lead to the underrunning or exceeding the switching thresholds. To avoid undesired switching of the backing pump you can operate the interval operation using a switching delay, depending on the process or application requirements. The delay is depending on a permanently uninterrupted exceedence or undershot of the specified switching threshold.

- Switch-off threshold, parameter **[P:710]**
 - Switch-on threshold, parameter **[P:711]**
 - Delay 8 s.
1. Set the parameter **[P:025]** to "3".
 2. Use this signal for the control of a fore-vacuum safety valve.

7.2.9 Backing pump standby mode

In case you are using a Pfeiffer Vacuum backing pump with rotation speed control, this can be used in standby mode by configuring the digital output **[P:019]** or **[P:024]**. The power consumption of the turbopump has a direct influence on the rotation speed of the backing pump.

Configuring the stand-by mode

1. Establish the connection of the backing pump using a suitable connecting cable.
2. Set parameter **[P:019]** or **[P:024]** to "22" (backing pump stand-by mode).
3. Find the respective standby rotation speed from the corresponding operating instructions of the backing pump.

7.2.10 Operation with accessories



Installation and operation of accessories

Pfeiffer Vacuum offers a series of special, compatible accessories for its products.

- Information and ordering options for approved [accessories](#) you can find online.
- The following accessories are not included in the scope of delivery.

Procedure

- Carry out the configuration of the connections via parameter **[P:035]**, **[P:036]**, **[P:037]** or **[P:038]**.

Configuring the heating

Activation of the connected housing heating depends on the rotation speed switch point 1 (factory setting $80\% \times f_{Nominal}$).

- Switch the heating on or off with parameter **[P:001]**.

Configuring the fan

1. Set the selected parameter to "0" for continuous operation of the fan.
2. Set the selected parameter to "4" for temperature-controlled operation of the fan.

Configuring the sealing gas valve

- Using parameter **[P:050]**, switch a connected sealing gas valve on or off via the pre-configured output.

Monitoring the sealing gas

1. Set the selected parameter to "13".
2. Set the parameter **[P:791]** to the desired sealing gas flow for the warning threshold.
3. Query the sealing gas flow via parameter **[P:337]**.

Configuring the bottom part heating

The accessory output controls the heating cartridges that maintain the bottom part of the turbopump at maximum temperature. The control is carried out according to pump-specific requirements, depending on the current power input of the vacuum pump and the switch point.

1. Set the selected parameter to "14".
2. Switch the heating on or off with parameter **[P:001]**.
3. Query the bottom part temperature via parameter **[P:330]**.

7.2.11 Venting modes

The function "pumping station" enables the venting mode of the turbopump after switching off. The signal output is carried out with a fixed delay.

Selecting the venting mode

1. Set parameter **[P:012]** to "1".
2. Select the venting mode with parameter **[P:030]** (3 possible modes).

Delayed venting

1. Configure the beginning and the time for the venting after "pumping station off" depending on the rotation speed of the turbopump.
2. Set parameter **[P:030]** to "0".
3. With parameter **[P:720]**, set the venting speed to the nominal rotation speed in %.
4. With parameter **[P:721]**, set the venting speed in s.

The venting valve opens for the set venting time. In case of a power failure, the venting starts when underrunning the set venting speed. The venting period depends on the residual energy delivered by the turning rotor. The venting process stops, when power is restored.

No venting

In this operating mode, the venting is deactivated.

- Set parameter **[P:030]** to "1".

Direct venting

Venting starts with a delay of 6 sec. after "pumping station off". When the pumping station function is switched back on, the venting valve closes automatically. After a power failure, the venting starts after falling below a fixed specified type-specific rotation speed. When power is restored, the venting process is continued.

- Set parameter **[P:030]** to "2".

7.3 Operation via "remote" connection

Operating the electronic drive unit remotely via "remote"

1. Remove the mating plug from the "remote" connection of the electronic drive unit.
2. Connect the remote control.
3. Observe the correct terminal lay-out.
4. Utilize the screened plug and cable.

7.3.1 +24 V DC output/pin 1

A connection with +24 VDC to pin 1 (active high) activates inputs 2–6, as well as the connections to pins 10, 13 and 14. Alternatively, they can be activated via an external PLC. "PLC High level" activates and "PLC Low level" deactivates the functions.

- PLC High level: +13 V to +33 V
- PLC High level: -33 V to +7 V

- Ri: 7 kΩ
- $I_{\max} < 210 \text{ mA}$ (with RS-485, where present)

7.3.2 Inputs

The digital inputs at the "remote" connection are used to switch various electronic drive unit functions. As a factory default, inputs DI1 – DI2 have that can be configured with the Pfeiffer Vacuum parameter set via Profibus or the RS-485 interface.

DI1 (release venting) / Pin 2

Status	Description
V+	Release venting (venting as per venting mode)
open	Venting blocked (no venting occurs)

Tbl. 37: DI1 (release venting) / Pin 2

DI motor pump/pin 3

With pin 4 activated (pumping station) and successfully completed self-test of the electronic drive unit, the turbopump is initiated. During operation the turbopump can be switched off and back on again, with the pumping station still active, without venting the turbopump.

Status	Description
V+	Turbo pump motor on
open	Turbo pump motor off

Tbl. 38: DI motor pump/pin 3

DI pumping station / Pin 4

Control of connected pumping station components (e.g. backing pump, venting valve, air cooling). If pin 3 (motor) is activated at the same time, the turbopump starts up. Any pending error messages are reset by eliminating the cause.

Status	Description
V+	Error acknowledgement and pumping station on
open	Pumping station off

Tbl. 39: DI pumping station / Pin 4

DI standby/pin 5

In standby mode, the turbo pump operates at a specified rotor speed $<$ nominal rotation speed. The factory setting and recommended operation is 66.7 % of the nominal rotation speed.

Status	Description
V+	Standby activated
open	Standby off, operation at nominal rotation speed

Tbl. 40: DI standby/pin 5

DI2 (heater)/pin 6

Status	Description
V+	Heater on
open	Heater off

Tbl. 41: DI2 (heater)/pin 6

DI3 (sealing gas)/pin 10

Status	Description
V+	Sealing gas valve open
open	Sealing gas valve closed

Tbl. 42: DI3 (sealing gas)/pin 10**DI malfunction acknowledgment/pin 13**

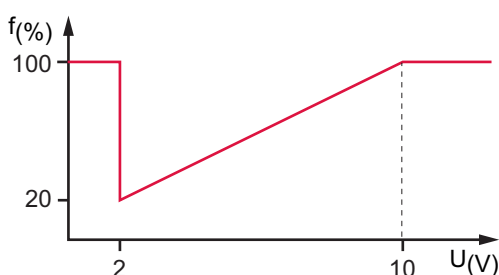
Status	Description
V+	Reset pending error messages when cause has been eliminated with a pulse of min. 500 ms duration.
open	Inactive

Tbl. 43: DI malfunction acknowledgment/pin 13**DI remote priority/pin 14**

Status	Description
V+	The "remote" connection has control priority over all other digital inputs.
open	Remote priority inactive

Tbl. 44: DI remote priority/pin 14**AI rotation speed setting mode/pins 7 and 11**

The analog input serves as a rotation speed setpoint for the turbopump. An input signal of 2 to 10 V between AI+ (pin 7) and AI- (pin 11) corresponds to a speed within the range of 20 to 100% of the nominal rotation speed. If the input is open or signals are below 2 V, the turbopump accelerates to the nominal rotation speed.

**Fig. 9: Rotation speed setting mode**

7.3.3 Outputs

The digital outputs at the "remote" connection have a maximum load limit of 24 V/50 mA per output. All outputs listed below are configurable with the Pfeiffer Vacuum parameter set via Profibus or the RS-485 interface (description relates to factory settings).

DO1 (rotation speed switchpoint reached) / Pin 8

Active high: After reaching the rotation speed switchpoint. Rotation speed switchpoint 1 has a factory setting of 80% of the nominal rotation speed. This can be used, for example, for a "Pump ready for operation" message.

DO2 (no error)/pin 9

When the supply voltage has been connected, digital output DO2 permanently outputs 24 V DC, which means "no error". Active low: in case of error (group error message).

DI remote priority active/pin 23

Active high: The "remote" connection takes priority over all other potentially connected control units (e.g. RS-485). For active low, the electronic drive unit ignores the "remote" connection.

AO1 analog output 0 to 10 V DC/pin 12

A speed-proportional voltage (0 to 10 V DC equals 0 to 100% $\times f_{\text{Nominal}}$) can be read out at the analog output (load $R \geq 10 \text{ k}\Omega$). Additional functions (optionally current/power) can be assigned to the analog output via DCU, HPU or PC.

7.3.4 Relay contacts (invertible)**Relay 1/pins 15, 16 and 17**

The contact between pin 16 and pin 15 is closed when the rotation speed drops below the switchpoint; relay 1 is inactive. The contact between pin 16 and pin 17 is closed when the speed reaches the rotation speed switchpoint; relay 1 is active.

Relay 2/pins 18, 19 and 20

The contact between pin 19 and pin 18 is closed when an error is pending; relay 2 is inactive. The contact between pin 19 and pin 20 is closed in case of trouble-free operation; relay 2 is active.

Relay 3/pins 21 and 22

The contact between pin 21 and pin 22 is closed in case of inactive warning messages; relay 3 is inactive. The contact between pin 21 and pin 22 is open when warnings are pending; relay 3 is active.

7.3.5 RS-485**⚠ DANGER****Danger to life from electric shock**

When establishing the voltages that exceed the specified safety extra-low voltage (according to IEC 60449 and VDE 0100), the insulating measures will be destroyed. There is a danger to life from electric shock at the communication interfaces.

► Connect only suitable devices to the bus system.

A Pfeiffer Vacuum display and control unit (DCU **or** HPU) **or** an external PC can be connected via pins 24 and 25 of the electronic drive unit's "remote" connection. A USB interface (PC) can be connected via the USB/RS-485-converter.

Designation	Value
Serial interface	RS-485
Baudrate	9600 Baud
Data word length	8 bit
Parity	none (no parity)
Start bits	1
Stop bits	1 – 2

Tbl. 45: RS-485 interface, features

Networking as RS-485 bus

The group address of the electronic drive unit is 962.

1. Install the devices according to the specification for RS-485 interfaces.
2. Make sure that all devices connected to the bus have different RS-485 device addresses [**P:797**].
3. Connect all devices to the bus with RS-485 D+ and RS-485 D-.

7.4 Switching on the turbopump

The function "pumping station" [**P:010**] comprises the turbopump operation with control of all connected accessory devices (e.g. backing pump).

Procedure

After successfully completing the self-test, the electronic drive unit resets pending and corrected error messages. The turbopump starts and all connected accessory devices start operation according to their configuration.

1. Set the parameter **[P:023]** to "1".
 - The parameter **[P:023]** switches on the motor of the turbopump.
2. Set the parameter **[P:010]** to "1".

7.5 Switching off the turbopump

Procedure

The electronic drive unit switches off the turbopump and activates pre-set accessory options (e.g. venting ON, backing pump OFF).

1. Set the parameter **[P:010]** to "0".
2. Wait until the turbopump comes to a complete standstill.
3. Disconnect the power supply according to the operating instructions of the turbopump or the power supply pack.

Disconnecting from the mains

- Disconnect the power supply pack from the mains to disconnect the current supply completely.

**Unplugging the mains plug**
















Unplugging the mains plug during running operation immediately de-energizes the power supply pack and the devices that are connected to it.

7.6 Operation monitoring




7.6.1 Operating mode display via LED





LEDs on the electronic drive unit show the basic operating states of the turbopump. A differentiated error and warning display is possible in case of operations with the Pfeiffer Vacuum display and control panel.

The Profibus interface features its own operating mode display in the form of an LED on the connecting socket of the electronic drive unit.

LED	Symbol	LED status	Display	Meaning
Green 		Off		Currentless
		On, flashing		"pumping station OFF", rotation speed ≤ 60 rpm
		On, inverse flashing		"pumping station ON", set rotation speed not reached
		On, constant		"pumping station ON", set rotation speed reached
		On, flashing		"pumping station OFF", speed > 60 rpm
Yellow 		Off		No warning
		On, constant		Warning
Red 		Off		No error, no warning
		On, constant		Error, malfunction

Tbl. 46: Behavior and meaning of the LEDs on the electronic drive unit

LED status	Display	Meaning
Off		Profibus on device side not active
Green flashing		Baud rate detected, no user data exchange
2x green flashing		Fail-safe

LED status	Display	Meaning
Green illuminated		User data exchange
Red flashing		No Baud rate detected
2x red flashing		Parameterization/configuration data incorrect
Red illuminated		Profibus not possible (invalid address, initialization error)

Tbl. 47: Behavior and meaning of the Profibus LED

7.6.2 Temperature monitoring

If threshold values are exceeded, output signals from temperature sensors bring the turbopump to a safe condition. Depending on the type, temperature thresholds for warning and error messages are immutably stored in the electronic drive unit. For information purposes, various status requests are set up in the parameter set.

- In order to avoid switching off the turbopump, the electronic drive unit already reduces the power consumption in case of exceeding the warning threshold for excess temperature.
 - Examples are an impermissible motor temperature, or impermissibly high housing temperature.
- Further reduction of drive power and thus decreasing speed can potentially lead to underrun the rotation speed switchpoint. The turbopump switches off.
- Exceeding the temperature threshold for error messages switches off the turbopump immediately.

8 Recycling and disposal

WARNING

Health hazard through poisoning from toxic contaminated components or devices

Toxic process media result in contamination of devices or parts of them. During maintenance work, there is a risk to health from contact with these poisonous substances. Illegal disposal of toxic substances causes environmental damage.

- ▶ Take suitable safety precautions and prevent health hazards or environmental pollution by toxic process media.
- ▶ Decontaminate affected parts before carrying out maintenance work.
- ▶ Wear protective equipment.



Environmental protection

You **must** dispose of the product and its components in accordance with all applicable regulations for protecting people, the environment and nature.

- Help to reduce the wastage of natural resources.
- Prevent contamination.

8.1 General disposal information

Pfeiffer Vacuum products contain materials that you must recycle.

- ▶ Dispose of our products according to the following:
 - Iron
 - Aluminium
 - Copper
 - Synthetic
 - Electronic components
 - Oil and fat, solvent-free
- ▶ Observe the special precautionary measures when disposing of:
 - Fluoroelastomers (FKM)
 - Potentially contaminated components that come into contact with media

8.2 Dispose of electronic drive unit

Electronic components and their housings contain material that must be recycled.

- ▶ Dispose of electronic components in a safe manner according to locally applicable regulations.

9 Malfunctions

9.1 General

WARNING

Risk of injury from parts moving after a power failure or troubleshooting

The "pumping station" function of the electronic drive unit will remain active after a power failure or if errors occur that shut down the vacuum pump or the system. When power is restored or after acknowledging a fault, the vacuum pump runs up automatically. There is a risk of injury to fingers and hands if they enter the operating range of rotating parts.

- ▶ Always keep the mains connection freely accessible so you can disconnect it at any time.
- ▶ Remove present mating plugs or bridges from the electronic drive unit possibly before the mains power returns, as these can cause an automatic run-up.
- ▶ Switch the pump off using the "Pumping station" function (parameter **[P:010]**).

Malfunctions of turbopump and electronic drive unit always result in a warning or error messages. In both cases, you receive an error code that you can read out via the interfaces of the electronic drive unit. Generally, the LEDs on the electronic drive unit show the operating messages. If an error occurs, the turbo pump and connected devices switch off. The selected venting mode starts after a preset delay.

9.2 Error codes

Errors (** Error E—— **) always cause the connected peripheral devices to be switched off.

Warnings (* Warning F —— *) do not cause components to be switched off.

Handling malfunction messages

1. Read out error codes via Pfeiffer Vacuum control units or a PC.
2. Remove the cause of the malfunction.
3. Reset the malfunction message with parameter **[P:009]**.
 - Use preconfigured interfaces or screen tiles on Pfeiffer Vacuum control units.

Error code	Problem	Possible causes	Remedy
Err001	Excess rotation speed	<ul style="list-style-type: none"> Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service Only acknowledge for rotational speed $f = 0$
Err002	Excess voltage	<ul style="list-style-type: none"> Incorrect power supply pack Incorrect mains input voltage 	<ul style="list-style-type: none"> Check the power supply pack type Check the mains input voltage Only acknowledge for rotational speed $f = 0$
Err006	Run-up error	<ul style="list-style-type: none"> Run-up time threshold set too low Gas flow in recipients through leaks or open valves Still below speed-control switch point run-up time expires 	<ul style="list-style-type: none"> Adjust run-up time to process conditions Check vacuum chambers for leaks and closed valves Adjust rotation speed switch point
Err007	Operating fluid low	<ul style="list-style-type: none"> Operating fluid low 	<ul style="list-style-type: none"> Check operating fluid Only acknowledge for rotational speed $f = 0$
Err008	Electronic drive unit - turbopump connection faulty	<ul style="list-style-type: none"> Connection to turbopump faulty 	<ul style="list-style-type: none"> Check the connections Only acknowledge for rotational speed $f = 0$
Err010	Internal device error	<ul style="list-style-type: none"> Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service Only acknowledge for rotational speed $f = 0$
Err021	Electronic drive unit does not detect turbopump	<ul style="list-style-type: none"> Incompatible software version Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service Only acknowledge for rotational speed $f = 0$
Err041	Drive fault	<ul style="list-style-type: none"> Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service Only acknowledge for rotational speed $f = 0$

Error code	Problem	Possible causes	Remedy
Err043	Internal configuration error	<ul style="list-style-type: none"> Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service
Err044	Excess temperature, electronics	<ul style="list-style-type: none"> Insufficient cooling 	<ul style="list-style-type: none"> Improve the cooling Check the operating conditions
Err045	Excess temperature, motor	<ul style="list-style-type: none"> Insufficient cooling 	<ul style="list-style-type: none"> Improve the cooling Check the operating conditions
Err046	Internal initialization error	<ul style="list-style-type: none"> Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service
Err073	Axial magnetic bearing overload	<ul style="list-style-type: none"> Rate of pressure rise too high 	<ul style="list-style-type: none"> Check the operating conditions Only acknowledge for rotational speed $f = 0$
Err074	Radial magnetic bearing overload	<ul style="list-style-type: none"> Rate of pressure rise too high 	<ul style="list-style-type: none"> Check the operating conditions Only acknowledge for rotational speed $f = 0$
Err089	Rotor instable	<ul style="list-style-type: none"> Impacts, vibrations Device defective 	<ul style="list-style-type: none"> Check the operating conditions Contact Pfeiffer Vacuum Service
Err091	Internal device error	<ul style="list-style-type: none"> Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service
Err092	Unknown connection panel	<ul style="list-style-type: none"> Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service
Err093	Motor temperature evaluation faulty	<ul style="list-style-type: none"> Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service
Err094	Electronics temperature evaluation faulty	<ul style="list-style-type: none"> Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service
Err098	Internal communication error	<ul style="list-style-type: none"> External faults Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service Only acknowledge for rotational speed $f = 0$
Err106	High rotor temperature	<ul style="list-style-type: none"> High gas throughput Impermissible thermal radiation Impermissible magnetic field 	<ul style="list-style-type: none"> Check the operating conditions
Err107	Final stage group error	<ul style="list-style-type: none"> External faults Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service Only acknowledge for rotational speed $f = 0$
Err108	Rotation speed measurement faulty	<ul style="list-style-type: none"> External faults Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service Only acknowledge for rotational speed $f = 0$
Err109	Software not released	<ul style="list-style-type: none"> Faulty software update 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service
Err110	Operating fluid evaluation faulty	<ul style="list-style-type: none"> Operating fluid sensor faulty 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service Only acknowledge for rotational speed $f = 0$
Err111	Operating fluid pump communication error	<ul style="list-style-type: none"> External faults Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service Only acknowledge for rotational speed $f = 0$
Err112	Operating fluid pump group error	<ul style="list-style-type: none"> External faults Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service Only acknowledge for rotational speed $f = 0$
Err113	Rotor temperature evaluation faulty	<ul style="list-style-type: none"> Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service
Err114	Final stage temperature evaluation faulty	<ul style="list-style-type: none"> Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service
Err117	Excess temperature, pump lower part	<ul style="list-style-type: none"> Insufficient cooling 	<ul style="list-style-type: none"> Improve the cooling Check the operating conditions
Err118	Excess temperature, final stage	<ul style="list-style-type: none"> Insufficient cooling 	<ul style="list-style-type: none"> Improve the cooling Check the operating conditions
Err119	Excess temperature, bearing	<ul style="list-style-type: none"> Insufficient cooling Incorrect gas mode selected Insufficient sealing gas flow 	<ul style="list-style-type: none"> Improve the cooling Check the operating conditions
Err143	Operating fluid pump excess temperature	<ul style="list-style-type: none"> Insufficient cooling 	<ul style="list-style-type: none"> Improve the cooling Check the operating conditions Only acknowledge for rotational speed $f = 0$
Err777	Nominal rotation speed not confirmed	<ul style="list-style-type: none"> Nominal rotation speed not confirmed after replacing the electronic drive unit 	<ul style="list-style-type: none"> Confirm the nominal rotation speed with [P:777] Only acknowledge for rotational speed $f = 0$

Error code	Problem	Possible causes	Remedy
Err800	Magnetic bearing overflow	<ul style="list-style-type: none"> Impacts, vibrations Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service Check the operating conditions Only acknowledge for rotational speed $f = 0$
Err802	Magnetic bearing sensor technology fault	<ul style="list-style-type: none"> Calibration values invalid Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service Perform a calibration procedure Only acknowledge for rotational speed $f = 0$
Err810	Internal configuration error	<ul style="list-style-type: none"> Incompatible software version 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service Only acknowledge for rotational speed $f = 0$
Err815	Magnetic bearing overflow	<ul style="list-style-type: none"> Impacts, vibrations Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service Check the operating conditions Only acknowledge for rotational speed $f = 0$
Err890	Safety bearing worn	<ul style="list-style-type: none"> Safety bearing wear > 100% 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service
Err891	Rotor imbalance too high	<ul style="list-style-type: none"> Rotor imbalance > 100% 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service Only acknowledge for rotational speed $f = 0$

Tbl. 48: Error messages of the electronic drive unit

Error code	Problem	Possible causes	Remedy
Wrn001	TMS heat-up time expired	<ul style="list-style-type: none"> Internal timer for heat-up monitoring exceeded 	<ul style="list-style-type: none"> Check the operating conditions Check the mains input voltage
Wrn003	TMS temperature invalid	<ul style="list-style-type: none"> TMS temperature not in the permissible range between 5 °C and 85 °C TMS temperature sensor defective 	<ul style="list-style-type: none"> Check the operating conditions Contact Pfeiffer Vacuum Service
Wrn007	Undervoltage or power failure	<ul style="list-style-type: none"> Mains failure Power supply pack dimensioned insufficiently 	<ul style="list-style-type: none"> Check the power supply pack type Check the mains input voltage
Wrn016	Accessory configuration invalid	<ul style="list-style-type: none"> Impermissible configuration of the accessory outputs 	<ul style="list-style-type: none"> Check the configuration of all accessory outputs
Wrn018	Operating supremacy conflict	<ul style="list-style-type: none"> Pumping station switched on with [P:010] while E74 input "start/stop" is off (opened) 	<ul style="list-style-type: none"> Switch on the pumping station via E74 "start/stop" Switch [P:010] off
Wrn021	Blocking signal invalid	<ul style="list-style-type: none"> Signal of the blocking signal monitoring outside the valid range 	<ul style="list-style-type: none"> Check the connections of the sealing gas monitoring Check the sealing gas supply
Wrn034	Sealing gas flow too low	<ul style="list-style-type: none"> Signal of the sealing gas monitoring valid but below the set threshold [P:791] 	<ul style="list-style-type: none"> Check and improve the sealing gas supply
Wrn045	Motor high temperature	<ul style="list-style-type: none"> Insufficient cooling 	<ul style="list-style-type: none"> Improve the cooling Check the operating conditions
Wrn076	Electronics high temperature	<ul style="list-style-type: none"> Insufficient cooling 	<ul style="list-style-type: none"> Improve the cooling Check the operating conditions
Wrn089	Imbalance high	<ul style="list-style-type: none"> Rotor imbalance 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service
Wrn097	Invalid pump information	<ul style="list-style-type: none"> Internal communication error 	<ol style="list-style-type: none"> Shut down pumping station Wait until the turbopump comes to a standstill Disconnect the power supply If this reoccurs, contact Pfeiffer Vacuum Service
Wrn098	Incomplete pump information	<ul style="list-style-type: none"> Internal communication error 	<ol style="list-style-type: none"> Shut down pumping station Wait until the turbopump comes to a standstill Disconnect the power supply If this reoccurs, contact Pfeiffer Vacuum Service
Wrn100	Minimum speed not reached	<ul style="list-style-type: none"> Settings of the set rotation speed below the pump-specific minimum speed 	<ul style="list-style-type: none"> Check [P:707] or [P:717] Obtain the valid rotation speed range from the technical data of the turbopump

Error code	Problem	Possible causes	Remedy
Wrn106	High rotor temperature	<ul style="list-style-type: none"> High gas throughput Impermissible thermal radiation Impermissible magnetic field 	<ul style="list-style-type: none"> Check the operating conditions
Wrn113	Inaccurate rotor temperature	<ul style="list-style-type: none"> Internal communication error 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service
Wrn115	Pump lower part temperature evaluation faulty	<ul style="list-style-type: none"> Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service
Wrn116	Bearing temperature evaluation faulty	<ul style="list-style-type: none"> Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service
Wrn117	Pump lower part high temperature	<ul style="list-style-type: none"> Insufficient cooling Incorrect gas mode selected 	<ul style="list-style-type: none"> Improve the cooling Check the operating conditions
Wrn118	Final stage high temperature	<ul style="list-style-type: none"> Insufficient cooling Incorrect gas mode selected 	<ul style="list-style-type: none"> Improve the cooling Check the operating conditions
Wrn119	Bearing high temperature	<ul style="list-style-type: none"> Insufficient cooling Incorrect gas mode selected Insufficient sealing gas flow 	<ul style="list-style-type: none"> Improve the cooling Check the operating conditions
Wrn143	High operating fluid pump temperature	<ul style="list-style-type: none"> Insufficient cooling 	<ul style="list-style-type: none"> Improve the cooling
Wrn168	High delay	<ul style="list-style-type: none"> Rate of pressure rise too high Venting rate too high 	<ul style="list-style-type: none"> Check the venting rate Adapt the venting rate to the pump
Wrn801	Braking transistor defective	<ul style="list-style-type: none"> Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service
Wrn806	Brake resistance defective	<ul style="list-style-type: none"> Device defective 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service
Wrn807	Calibration requirement	<ul style="list-style-type: none"> Calibration expired 	<ul style="list-style-type: none"> Calibrate the turbopump by starting from standstill
Wrn890	Safety bearing wear too high	<ul style="list-style-type: none"> Safety bearing wear > 75 % 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service
Wrn891	High rotor imbalance	<ul style="list-style-type: none"> Rotor imbalance > 75 % 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service

TbI. 49: Warning messages of the electronic drive unit

9.3 Warning and malfunction messages when operating with control units

Besides the device-specific warning and error messages on the electronic drive unit, additional messages are displayed with the connected control unit.

Indicator	Problem	Possible causes	Remedy
* Warning F110 *	Pressure gauge	<ul style="list-style-type: none"> Pressure gauge faulty Connection to the pressure gauge disconnected during operation 	<ul style="list-style-type: none"> Check the cable connection Carry out a restart with pressure gauge connected Replace the pressure gauge completely
** Error E040 **	Hardware error	<ul style="list-style-type: none"> external RAM faulty 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service
** Error E042 **	Hardware error	<ul style="list-style-type: none"> EPROM checksum incorrect 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service
** Error E043 **	Hardware error	<ul style="list-style-type: none"> E²PROM write error 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service
** Error E090 **	Internal device error	<ul style="list-style-type: none"> RAM not large enough Unit is connected to incorrect electronic drive unit 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service Connect the unit to the correct electronic drive unit
** Error E698 **	Communication error	<ul style="list-style-type: none"> Electronic drive unit is not responding 	<ul style="list-style-type: none"> Contact Pfeiffer Vacuum Service

TbI. 50: Warning and malfunction messages

10 Service solutions by Pfeiffer Vacuum

We offer first-class service

High vacuum component service life, in combination with low downtime, are clear expectations that you place on us. We meet your needs with efficient products and outstanding service.

We are always focused on perfecting our core competence – servicing of vacuum components. Once you have purchased a product from Pfeiffer Vacuum, our service is far from over. This is often exactly where service begins. Obviously, in proven Pfeiffer Vacuum quality.

Our professional sales and service employees are available to provide you with reliable assistance, worldwide. Pfeiffer Vacuum offers an entire range of services, from original replacement parts to service contracts.

Make use of Pfeiffer Vacuum service

Whether preventive, on-site service carried out by our field service, fast replacement with mint condition replacement products, or repair carried out in a Service Center near you – you have various options for maintaining your equipment availability. You can find more detailed information and addresses on our homepage, in the Pfeiffer Vacuum Service section.

You can obtain advice on the optimal solution for you, from your Pfeiffer Vacuum representative.

For fast and smooth service process handling, we recommend the following:



1. Download the up-to-date form templates.
 - Explanations of service requests
 - Service requests
 - Contamination declaration



- a) Remove and store all accessories (all external parts, such as valves, protective screens, etc.).
- b) If necessary, drain operating fluid/lubricant.
- c) If necessary, drain coolant.
2. Complete the service request and contamination declaration.



3. Send the forms by email, fax, or post to your local Service Center.

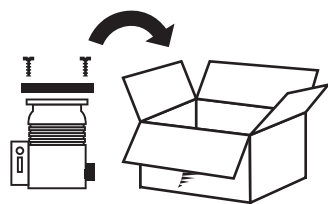


4. You will receive an acknowledgment from Pfeiffer Vacuum.

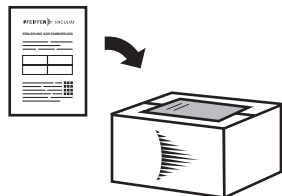
PFEIFFER VACUUM

Submission of contaminated products

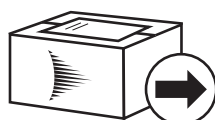
No microbiological, explosive, or radiologically contaminated products will be accepted. Where products are contaminated, or the contamination declaration is missing, Pfeiffer Vacuum will contact you before starting service work. Depending on the product and degree of pollution, **additional decontamination costs** may be incurred.



5. Prepare the product for transport in accordance with the provisions in the contamination declaration.
 - a) Neutralize the product with nitrogen or dry air.
 - b) Seal all openings with blind flanges, so that they are airtight.
 - c) Shrink-wrap the product in suitable protective foil.
 - d) Package the product in suitable, stable transport containers only.
 - e) Maintain applicable transport conditions.



6. Attach the contamination declaration to the **outside** of the packaging.



7. Now send your product to your local Service Center.



8. You will receive an acknowledgment/quotation, from Pfeiffer Vacuum.

PFEIFFER VACUUM

Our sales and delivery conditions and repair and maintenance conditions for vacuum devices and components apply to all service orders.

EC Declaration of Conformity

This declaration of conformity has been issued under the sole responsibility of the manufacturer.

Declaration for product(s) of the type:

Electronic drive unit

TC 400 PB

We hereby declare that the listed product satisfies all relevant provisions of the following **European Directives**.

Electromagnetic compatibility 2014/30/EU

Low voltage 2014/35/EC

Restriction of the use of certain hazardous substances 2011/65/EU

Restriction of the use of certain hazardous substances, delegated directive 2015/863/EU

Harmonized standards and applied national standards and specifications:

DIN EN ISO 12100 : 2011

DIN EN 62061 : 2016

DIN EN 1012-2 : 2011

DIN ISO 21360-1 : 2016

DIN EN IEC 61000-3-2 : 2019

ISO 21360-4 : 2018

DIN EN 61000-3-3 : 2020

DIN EN IEC 63000 : 2019

DIN EN 61010-1 : 2020

Semi F47-0200

DIN EN 61326-1 : 2013

Semi S2-0706

Signature:



(Daniel Sälzer)
Managing Director

Pfeiffer Vacuum GmbH
Berliner Straße 43
35614 Asslar
Germany

Asslar, 2022-12-07



UK Declaration of Conformity

This declaration of conformity has been issued under the sole responsibility of the manufacturer.

Declaration for product(s) of the type:

Electronic drive unit

TC 400 PB

We hereby declare that the listed product satisfies all relevant provisions of the following **British Directives**.

Electrical Equipment (Safety) Regulations 2016

Electromagnetic Compatibility Regulations 2016

The Restriction of the Use of Certain Hazardous Substances in Electrical and Electronic Equipment Regulations 2012

Applied standards and specifications:

EN ISO 12100:2010

EN IEC 62061:2021

EN 1012-2+A1:1996

ISO 21360-1:2020

EN IEC 61000-3-2+A1:2019

ISO 21360-4:2018

EN 61000-3-3+A2:2013

IEC 63000:2018

EN 61010-1+A1:2017

Semi F47-0200

EN IEC 61326-1:2021

Semi S2-0706

The manufacturer's authorized representative in the United Kingdom and the authorized agent for compiling the technical documentation is Pfeiffer Vacuum Ltd, 16 Plover Close, Interchange Park, MK169PS Newport Pagnell.

Signature:



(Daniel Sälzer)
Managing Director

Pfeiffer Vacuum GmbH
Berliner Straße 43
35614 Asslar
Germany

Asslar, 2022-12-07

**UK
CA**

VACUUM SOLUTIONS FROM A SINGLE SOURCE

Pfeiffer Vacuum stands for innovative and custom vacuum solutions worldwide, technological perfection, competent advice and reliable service.

COMPLETE RANGE OF PRODUCTS

From a single component to complex systems:

We are the only supplier of vacuum technology that provides a complete product portfolio.

COMPETENCE IN THEORY AND PRACTICE

Benefit from our know-how and our portfolio of training opportunities!

We support you with your plant layout and provide first-class on-site service worldwide.

ed. P - Date 2304 - P/N:PT0244BEN



Are you looking for a
perfect vacuum solution?
Please contact us

Pfeiffer Vacuum GmbH
Headquarters • Germany
T +49 6441 802-0
info@pfeiffer-vacuum.de

www.pfeiffer-vacuum.com